

Factored 3-Way Restricted Boltzmann Machines for Modeling Natural Images

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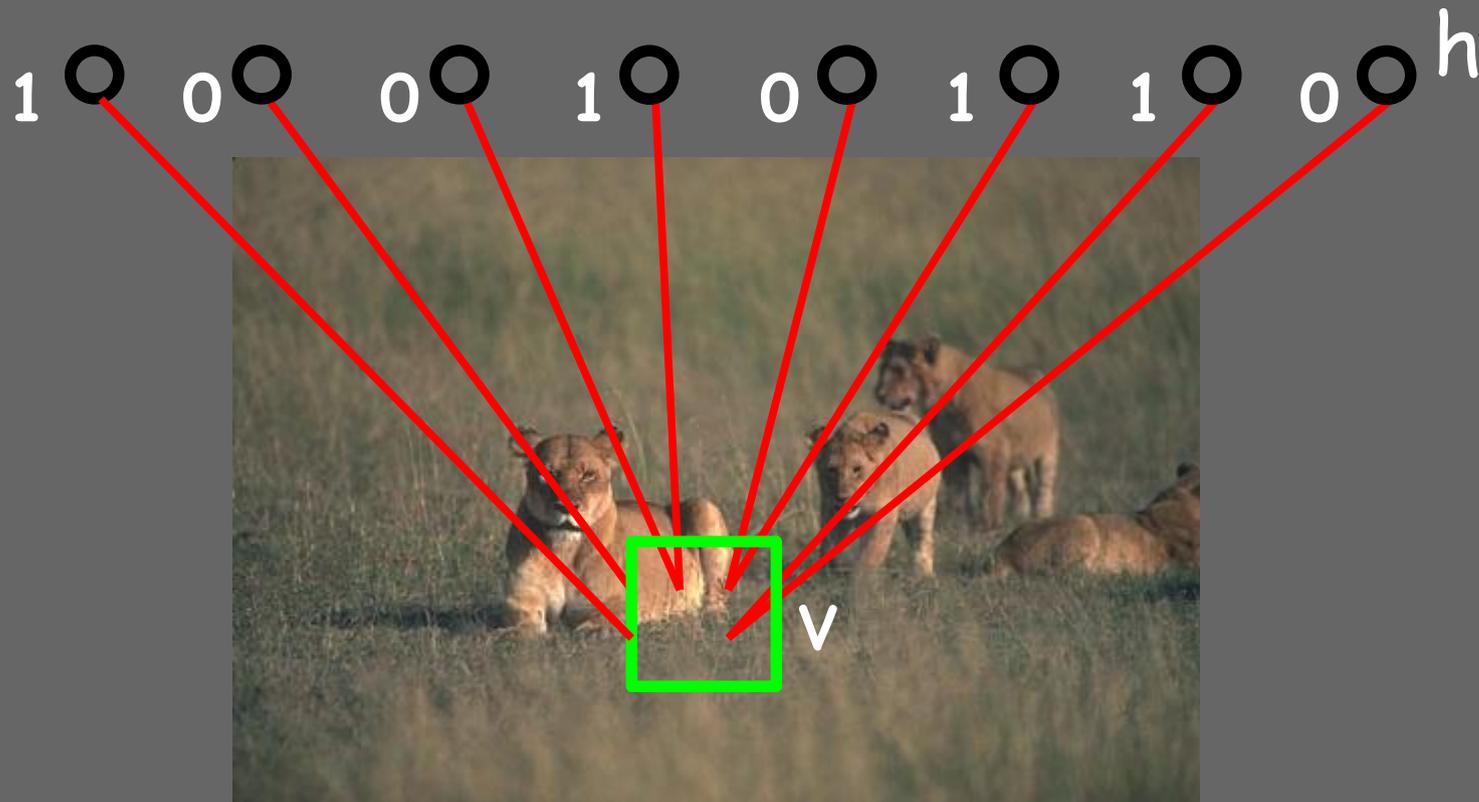
Marc'Aurelio Ranzato

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AISTATS - 14 May 2010

- Want to model natural images by using a generative model $p(\text{image } v; W)$

- Want to use the model to produce representations $p(\text{image } v, \text{hidden units } h; W)$



Goal: define $p(v, h)$

Q.: What is the key property of natural images?

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Q.: What is the key property of natural images?

A.: smoothness

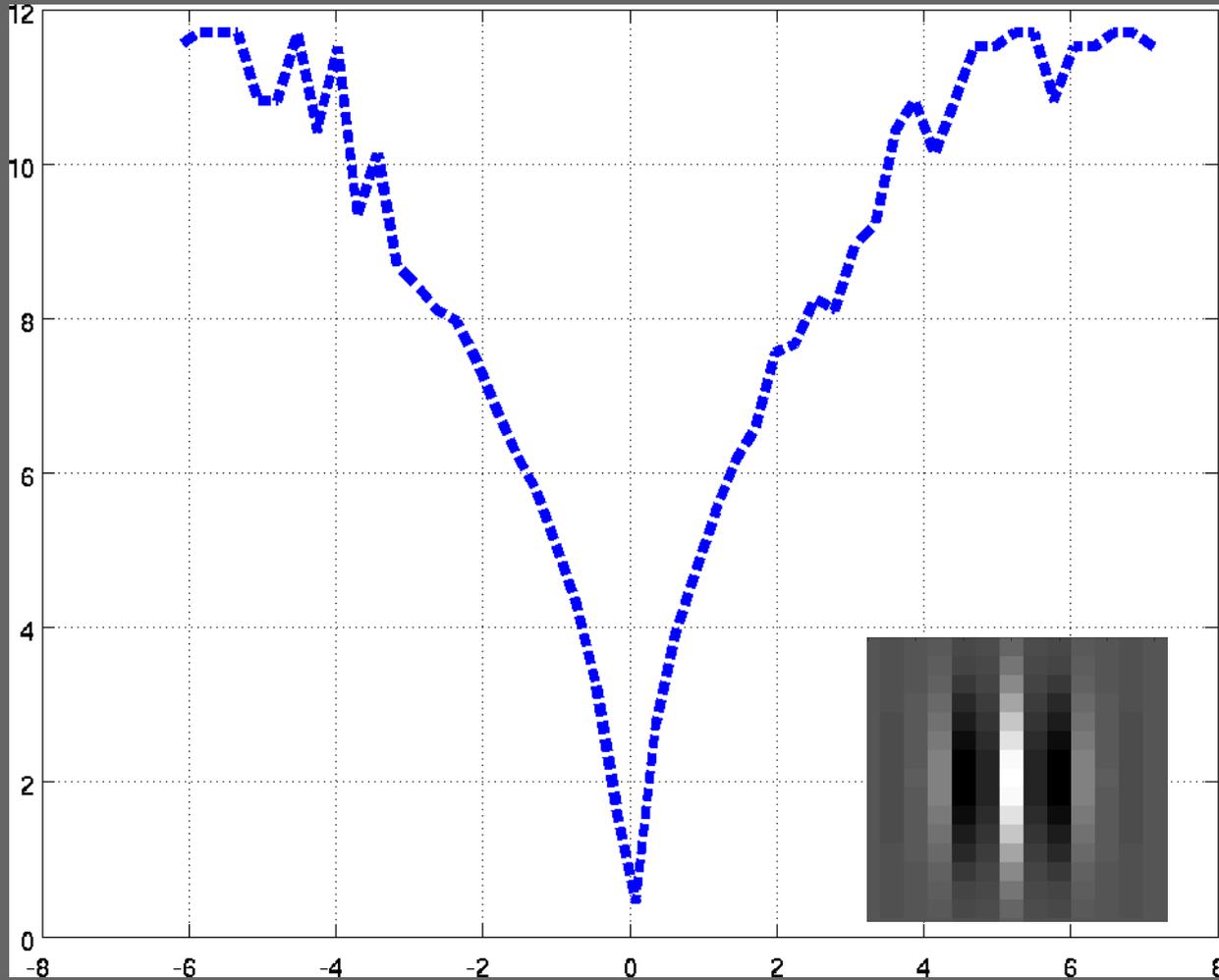


Most of the times, the value of one pixel can be well predicted from its neighbors



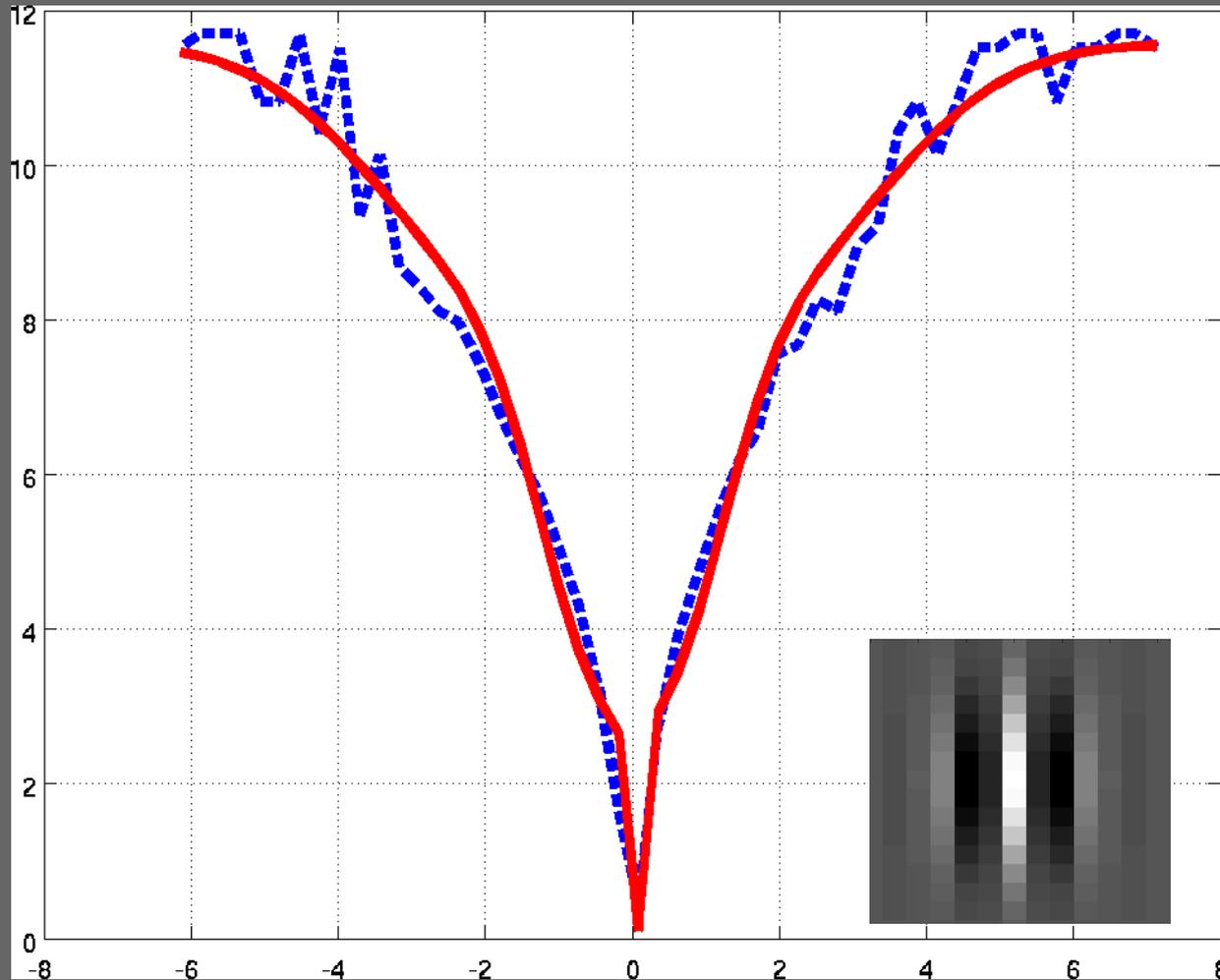
Most local neighborhoods
are smooth

- log(empirical p.d.f. of filter response)



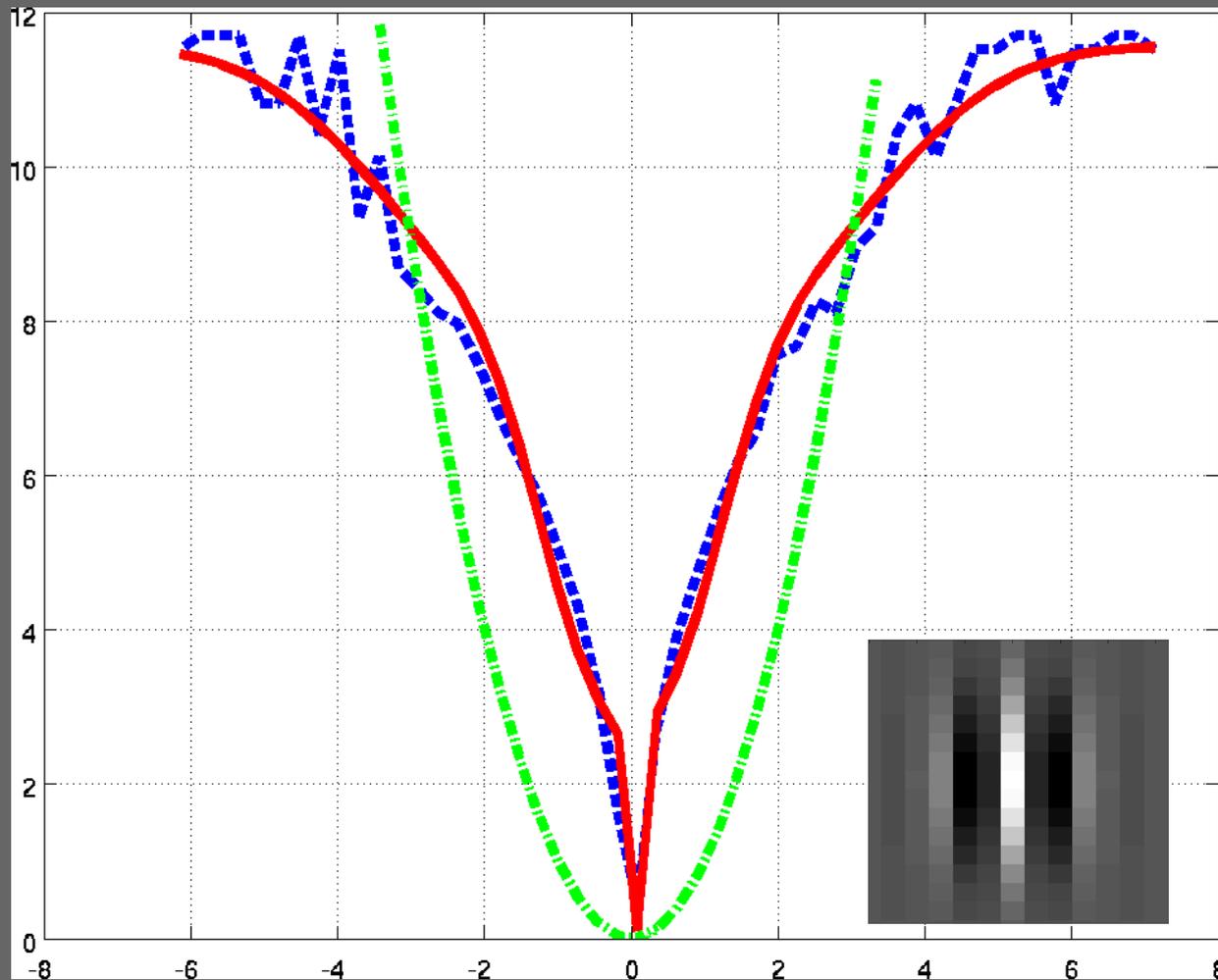
Finding an edge at this location and orientation is rare

- $\log(\text{empirical p.d.f. of filter response})$
- $\log(\text{fit of model p.d.f. to filter response})$



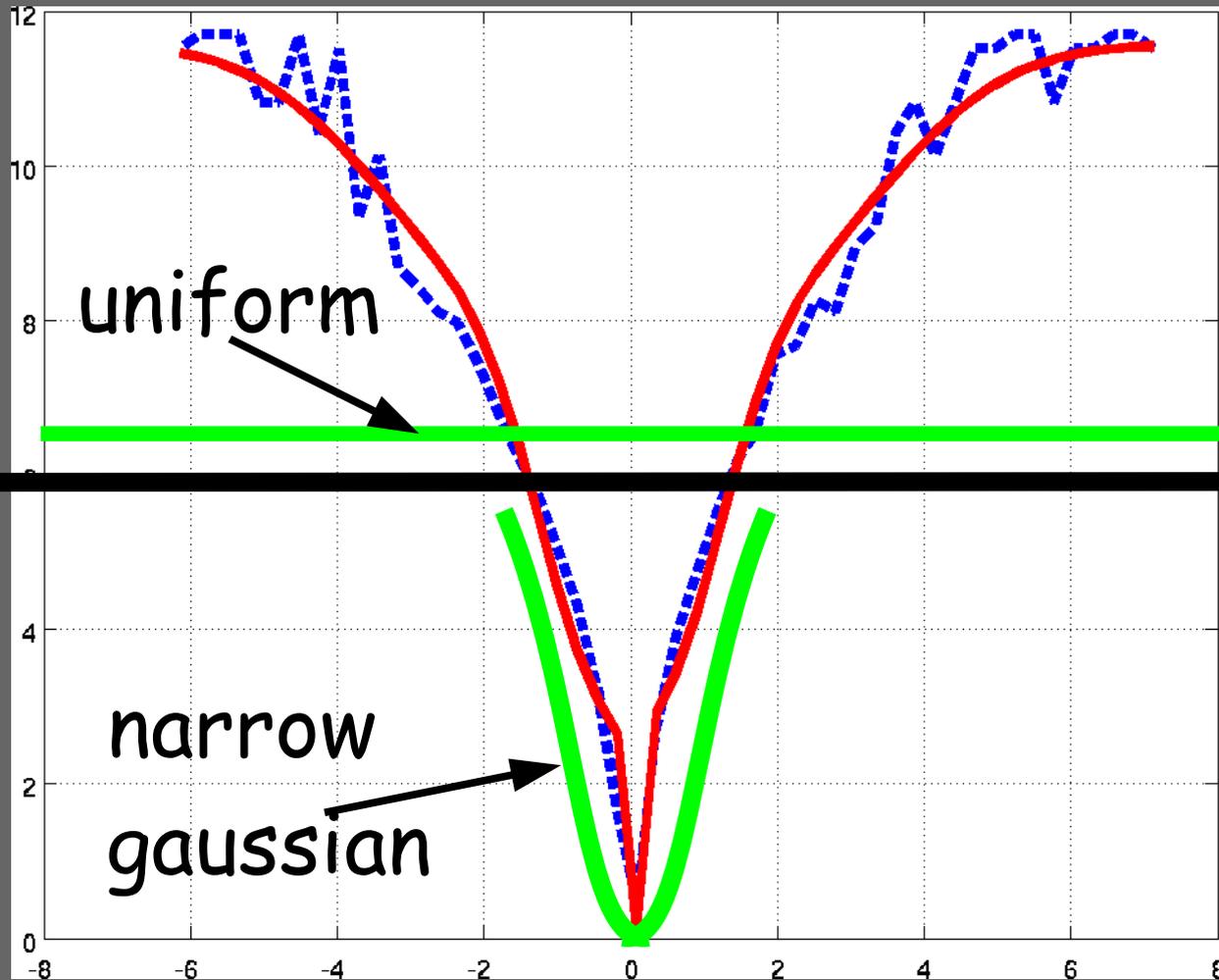
Finding an edge at this location and orientation is rare

- $\log(\text{empirical p.d.f. of filter response})$
- $\log(\text{fit of model p.d.f. to filter response})$
- $\log(\text{fit of Gaussian p.d.f. to filter response})$



Finding an edge at this location and orientation is rare

KEY IDEA: use "switch" hidden variable



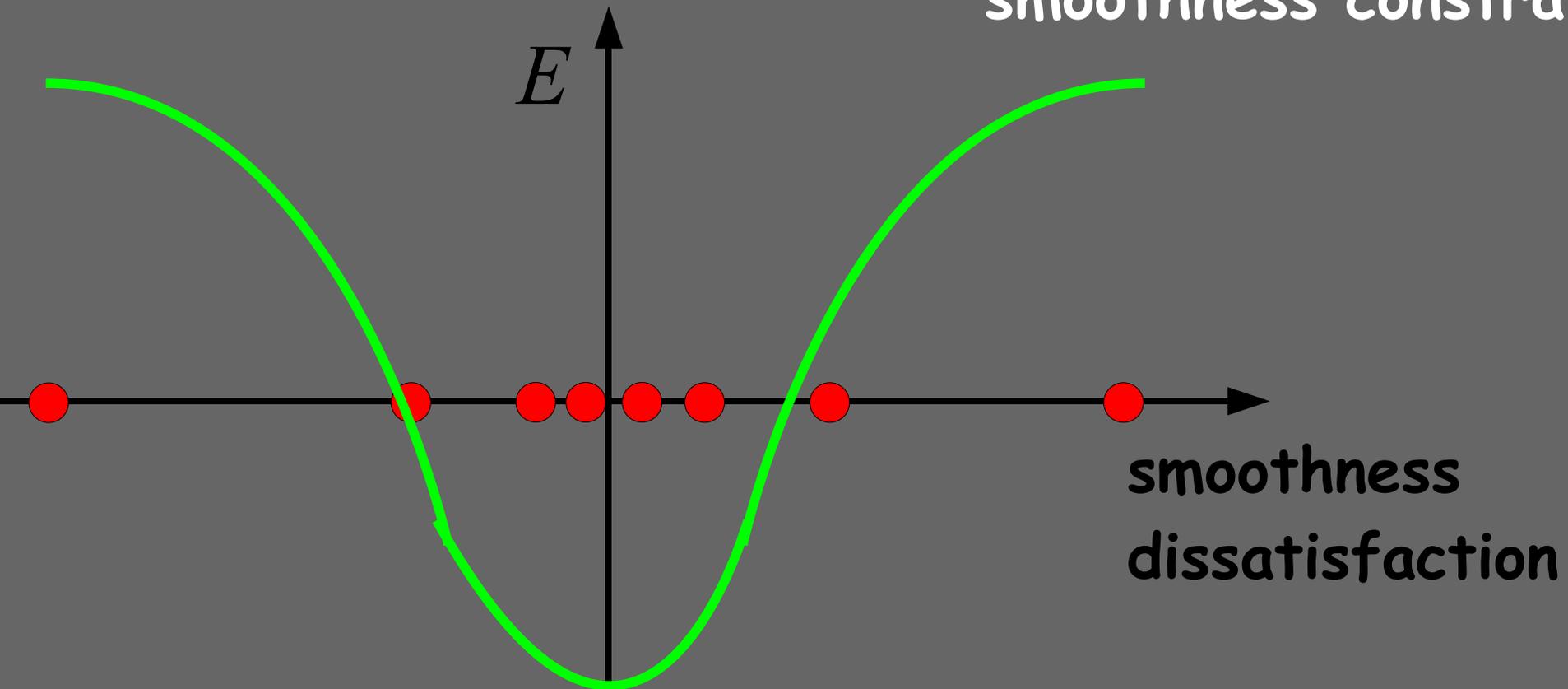
 $h = 0$
structured
images

 $h = 1$
smooth
images

Goal: define $p(v, h)$

$$p(v, h) \propto \exp[-E(v, h)]$$

Energy measures
dissatisfaction of
smoothness constraints



■ Smooth images are more likely

■ (Rare) structured images are unlikely but possible

- What is a good measure of smoothness dissatisfaction?
- Edges are not smooth.
E.g. what is a vertical edge?



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- Edges are not smooth.
E.g. **what is a vertical edge?**



polarity



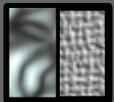
contrast



color



texture



- What is a good measure of smoothness dissatisfaction?
- Edges are not smooth.
E.g. what is a vertical edge?



Geoff: lack of horizontal "interpolation"

polarity



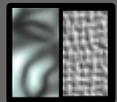
contrast



color



texture



...

■ What is a good measure of smoothness dissatisfaction?

■ Edges are not smooth.

E.g. what is a vertical edge?



Geoff: lack of horizontal "interpolation"



smoothness dissatisfaction

=

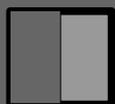
learned by set of linear filters

(patterns of "broken" interpolation)

polarity



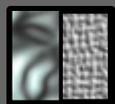
contrast



color



texture



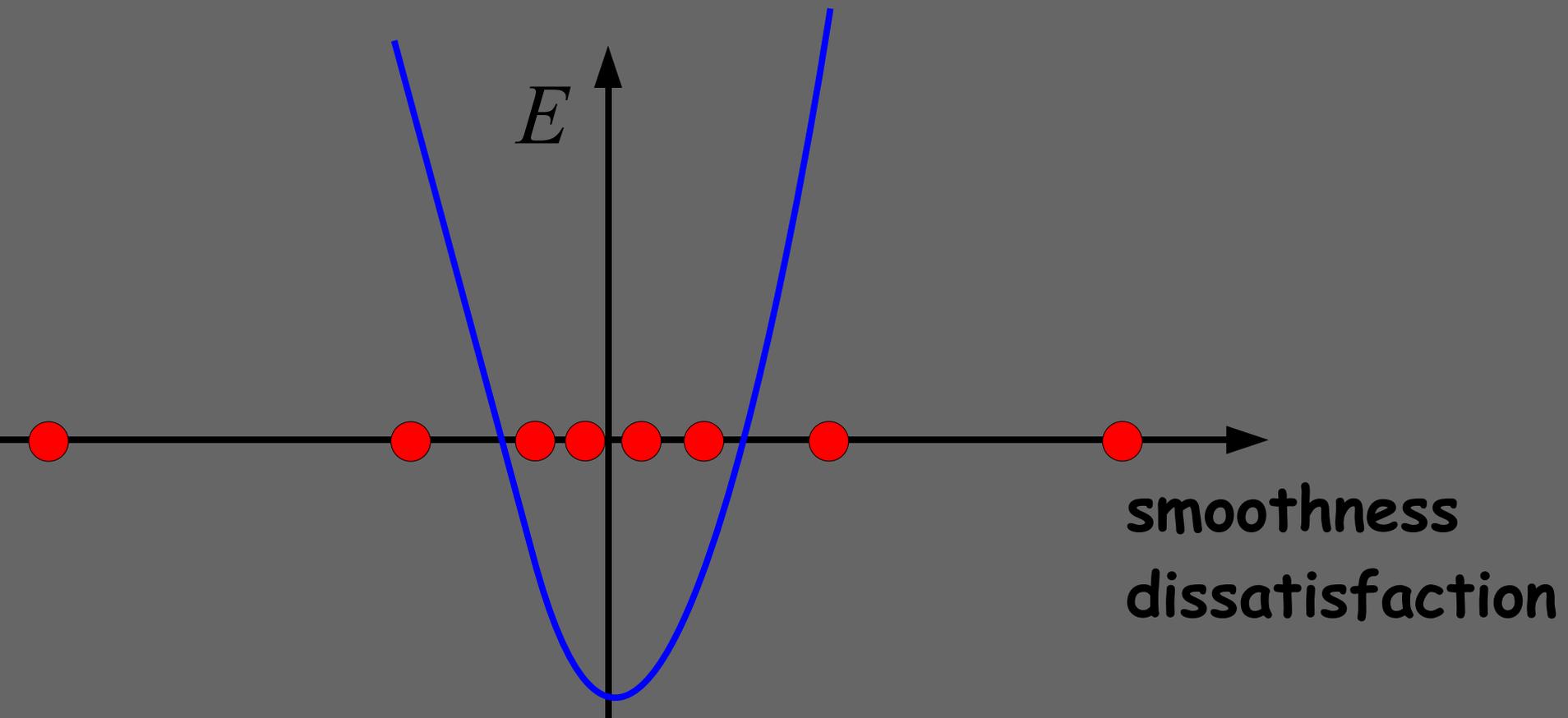
...

$$E = \sum_i \text{smoothness_dissatisfaction}_i - b_i$$

$$\text{smoothness_dissatisfaction}_i = W_i v$$

$$E = \sum_i \text{smoothness_dissatisfaction}_i^2 - b_i$$

$$\text{smoothness_dissatisfaction}_i = W_i v$$



$$E = \sum_i h_i \text{smoothness_dissatisfaction}_i^2 - h_i b_i$$

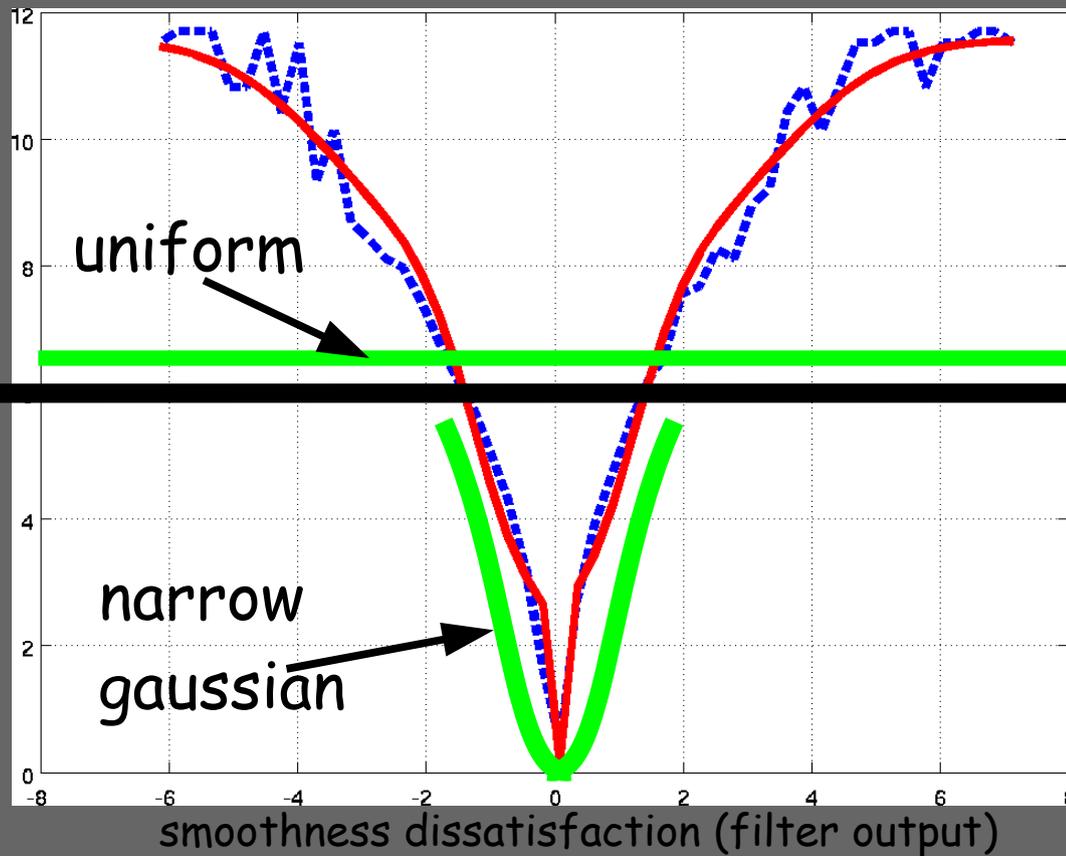
$$\text{smoothness_dissatisfaction}_i = W_i v$$

$h_i \in \{0, 1\}$ introduce hiddens to allow violations

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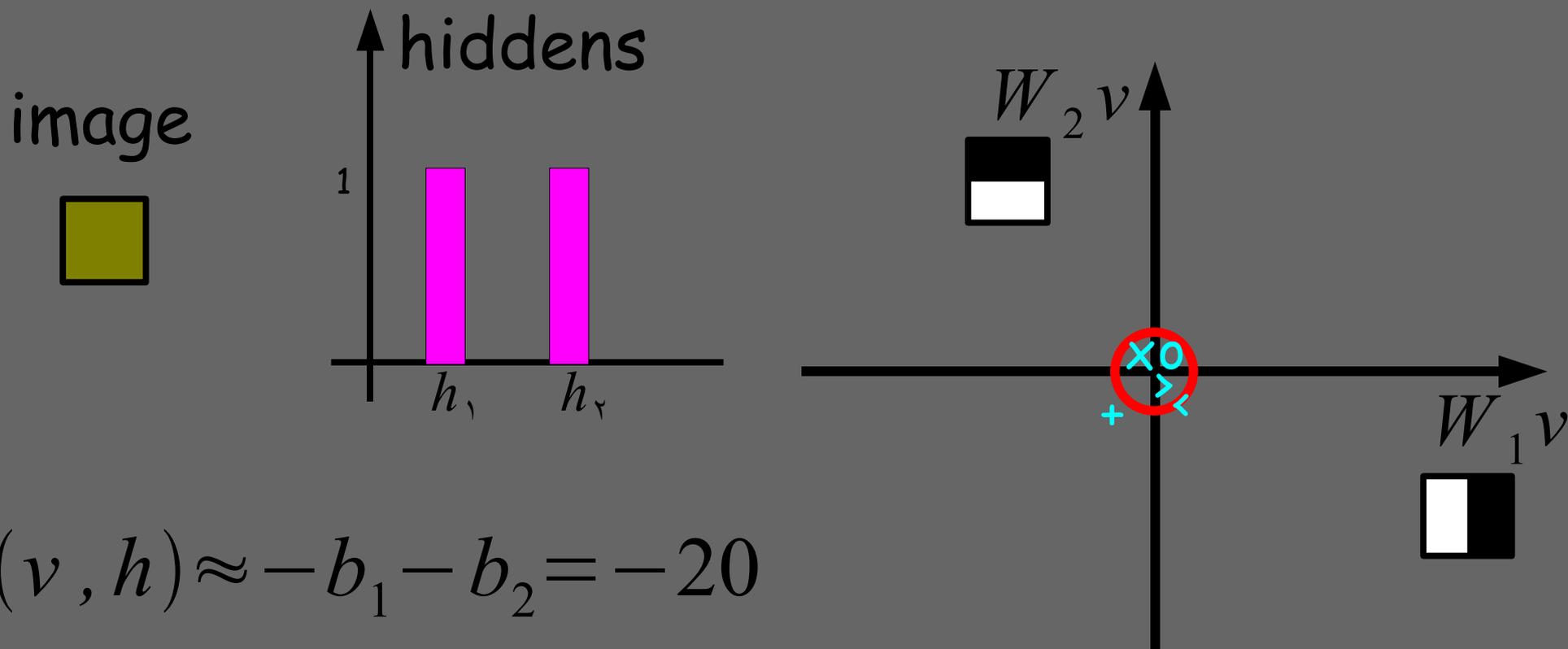


 $h = 0$
structured
images

 $h = 1$
smooth
images

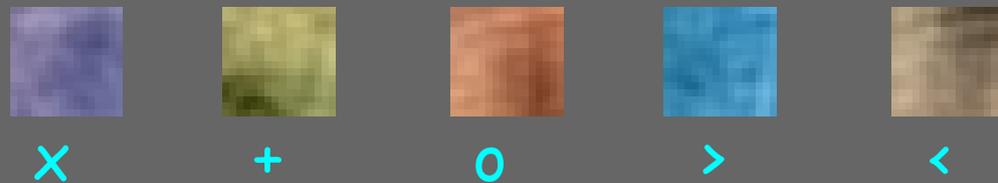
$$E = h_1 (W_1 v)^2 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

$$W_1 = \begin{bmatrix} \blacksquare & \blacksquare \\ \blacksquare & \blacksquare \end{bmatrix} \quad W_2 = \begin{bmatrix} \blacksquare & \blacksquare \\ \blacksquare & \blacksquare \end{bmatrix} \quad b_1 = 10 \quad b_2 = 10$$



$$E(v, h) \approx -b_1 - b_2 = -20$$

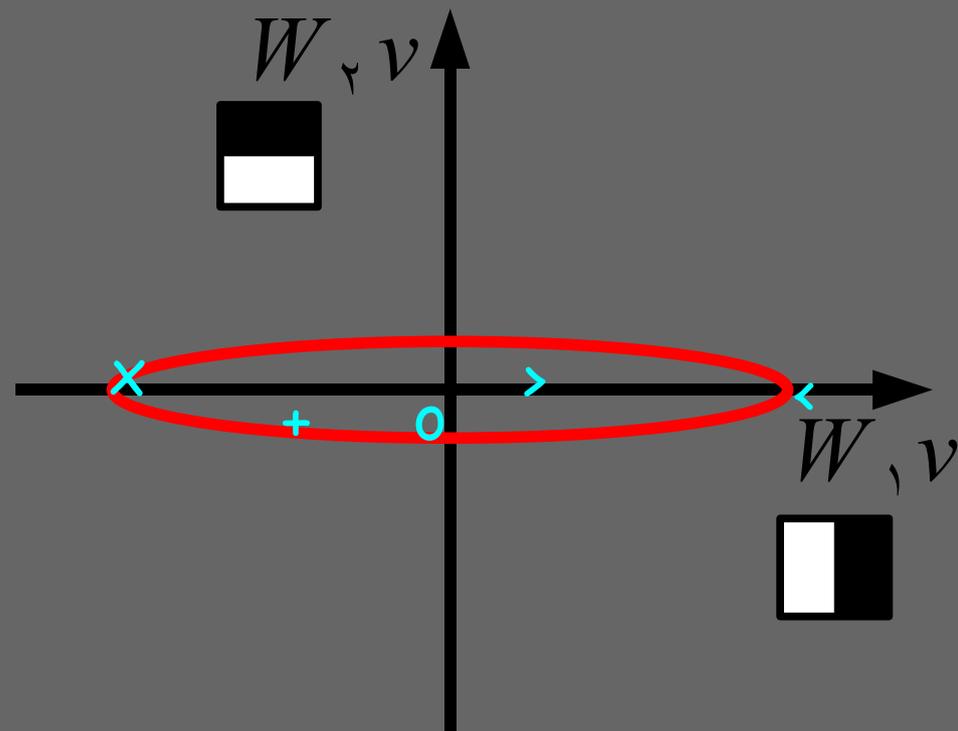
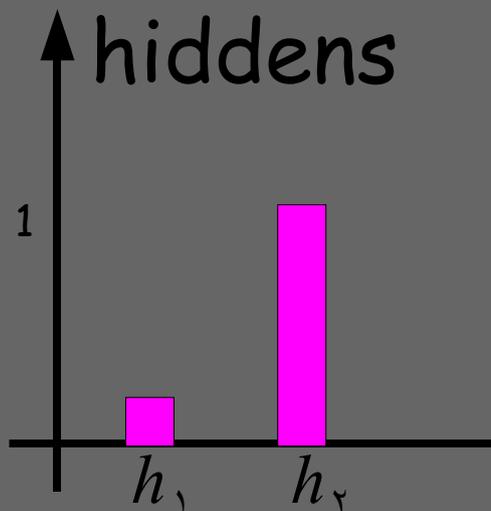
low energy



$$E = h_1 (W_1 v)^1 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

$$W_1 = \begin{bmatrix} \blacksquare & \blacksquare \\ \blacksquare & \blacksquare \end{bmatrix} \quad W_2 = \begin{bmatrix} \blacksquare & \blacksquare \\ \blacksquare & \blacksquare \end{bmatrix} \quad b_1 = 1 \quad b_2 = 1$$

image



$$E(v, h) \approx -b_2 = -1$$

higher energy

(h_1 gave discount!)



x



+



0



>



<

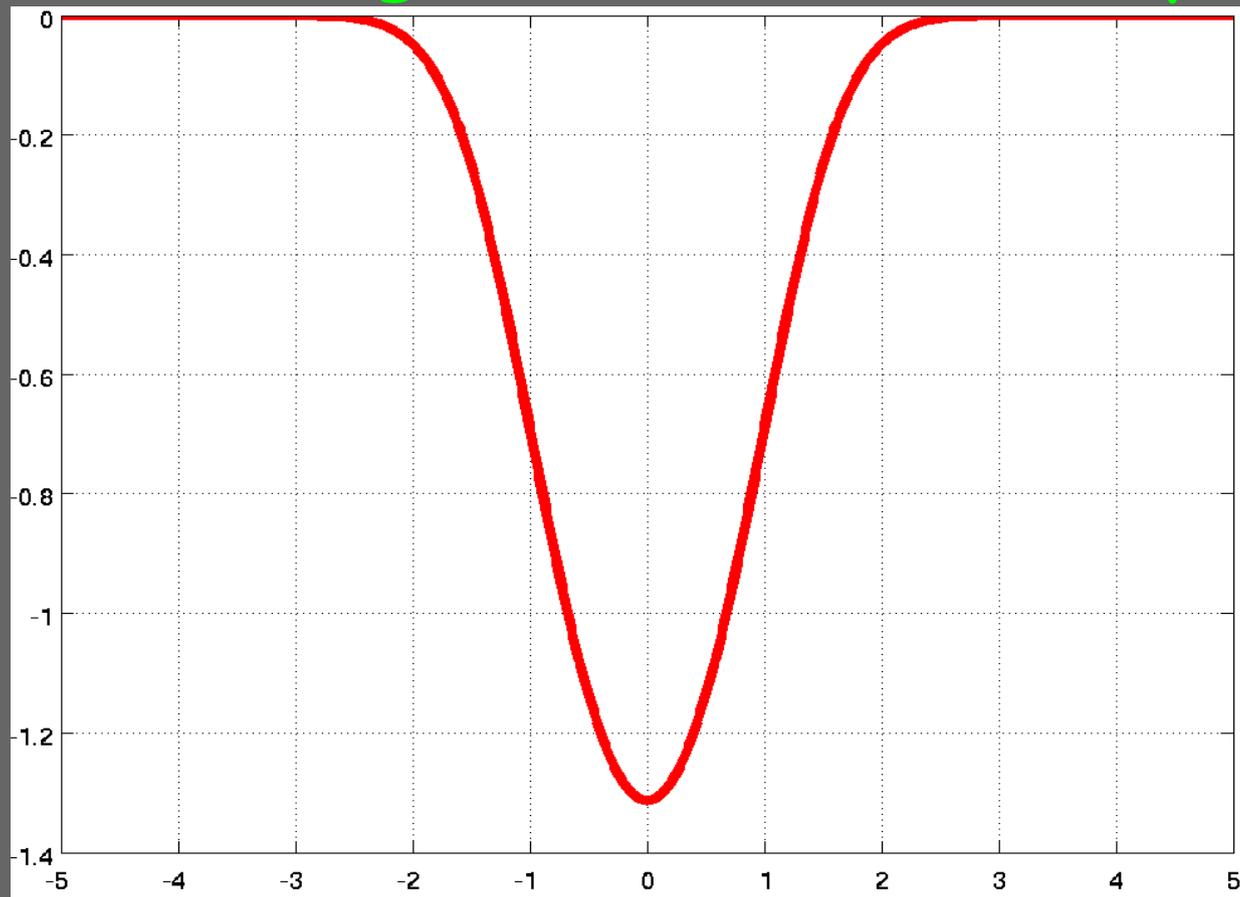
$$E = h_1 (W_1 v)^2 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

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Binary hidden units can be marginalized out exactly

$$-\log(p(v)) + k$$

We allow (rare)
smoothness
violations



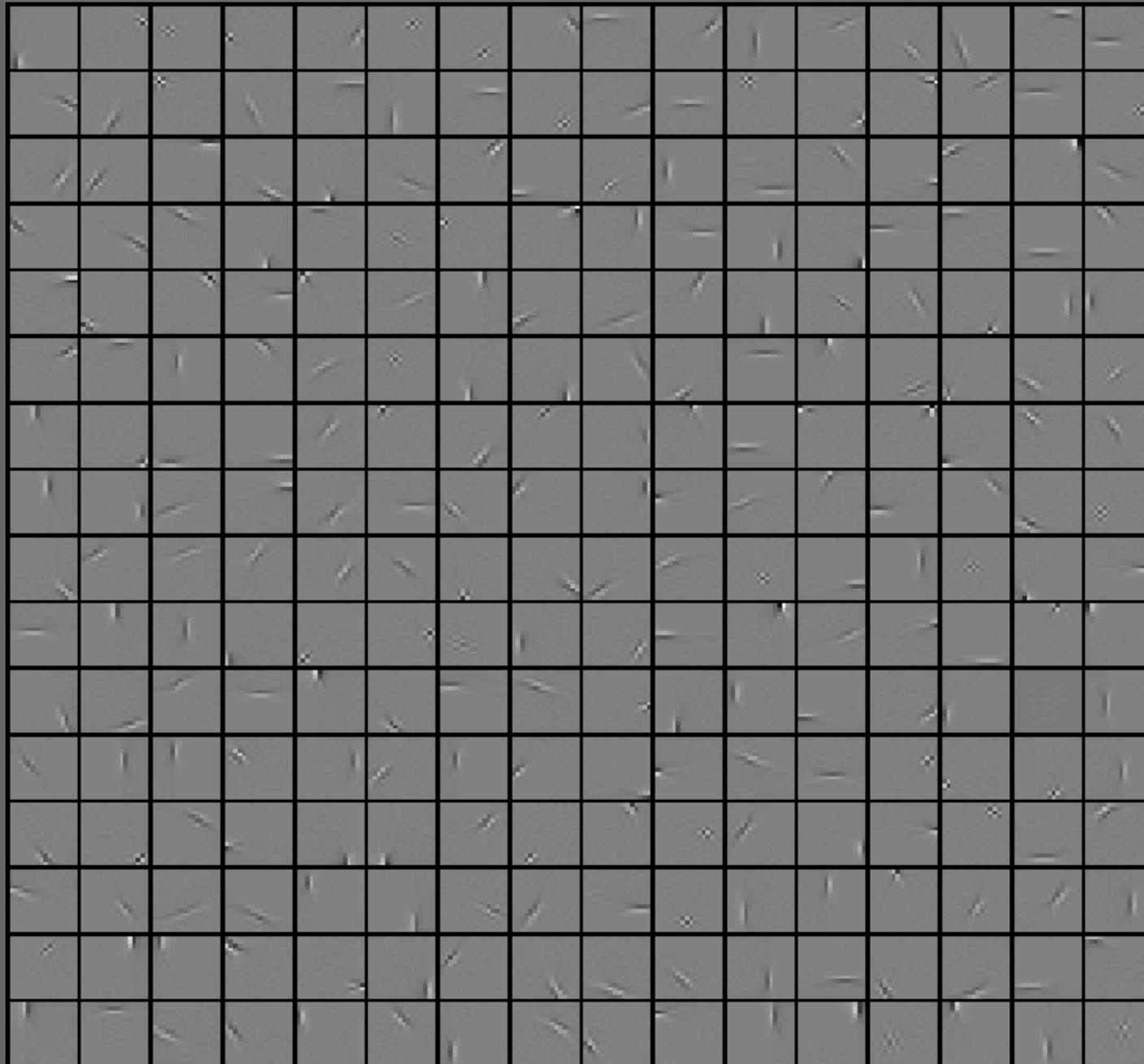
filter output

$$E = \frac{1}{2} \sum_k \sum_f h_k P_{fk} (W_f v)^2 - b_k h_k$$

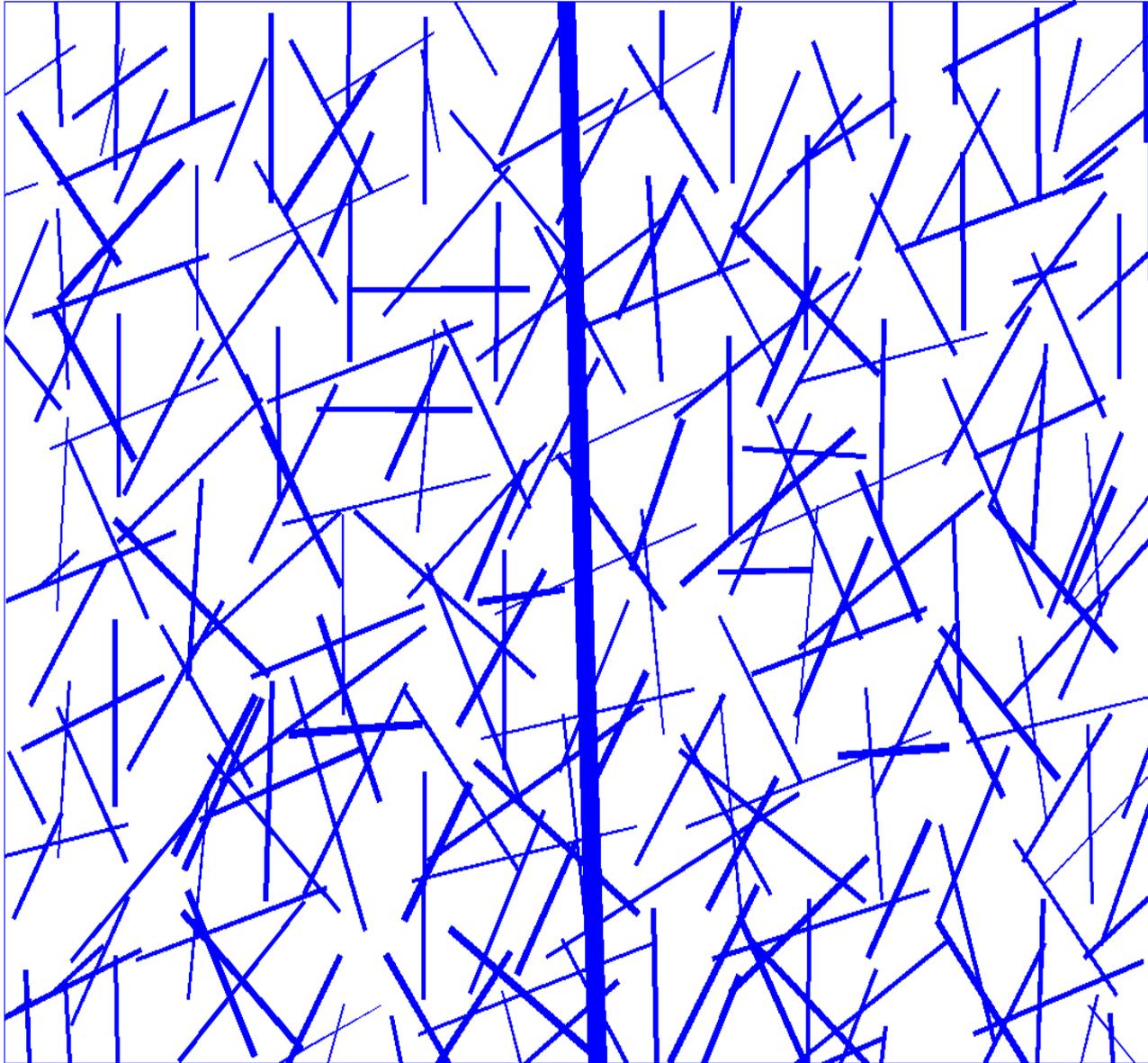
Learning: $\{W, P, b\}$

- approximate maximum likelihood
- Contrastive Divergence
- Hybrid Monte Carlo

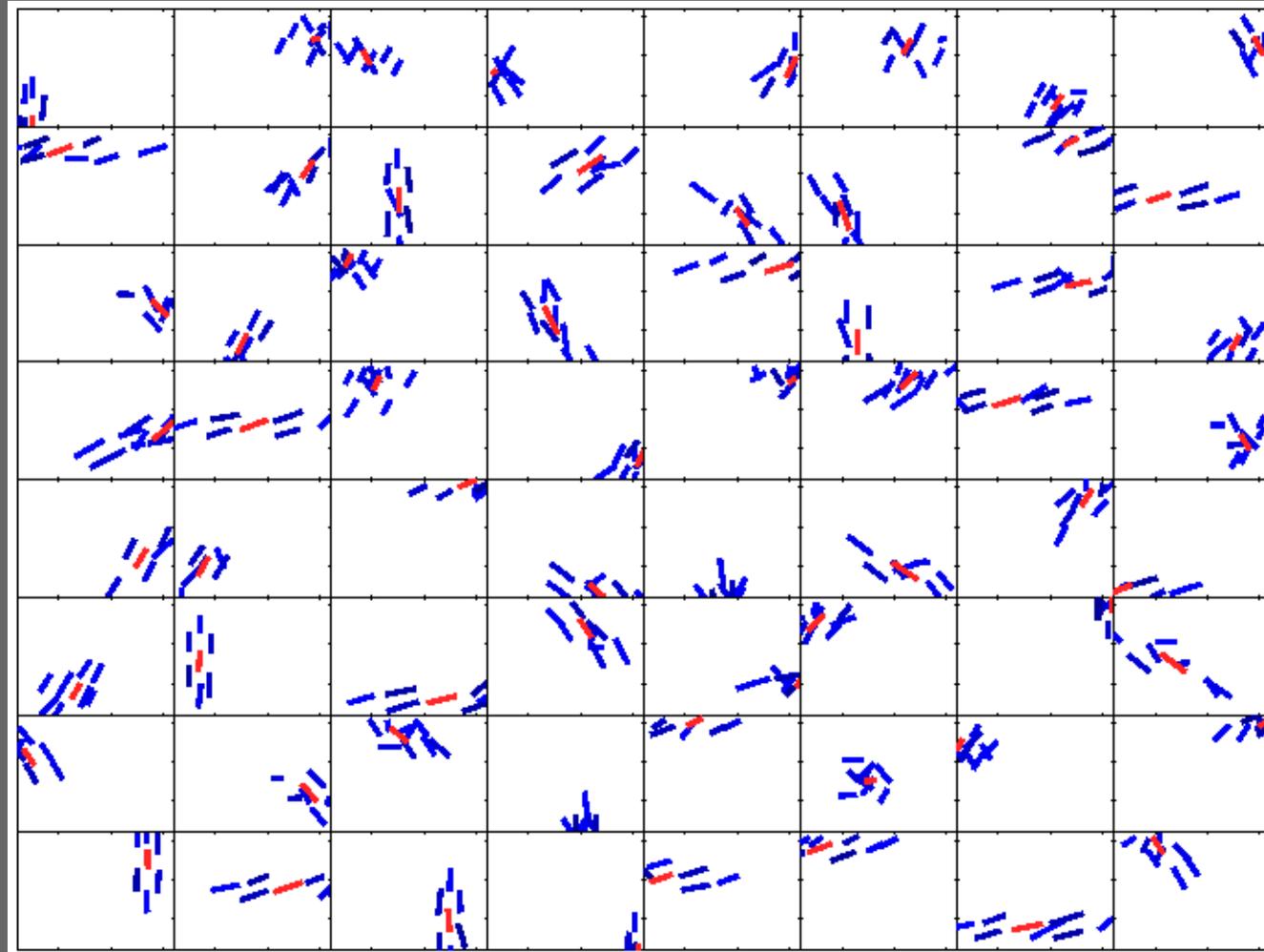
Learned filters (directions of smoothness dissatisfaction) on natural images



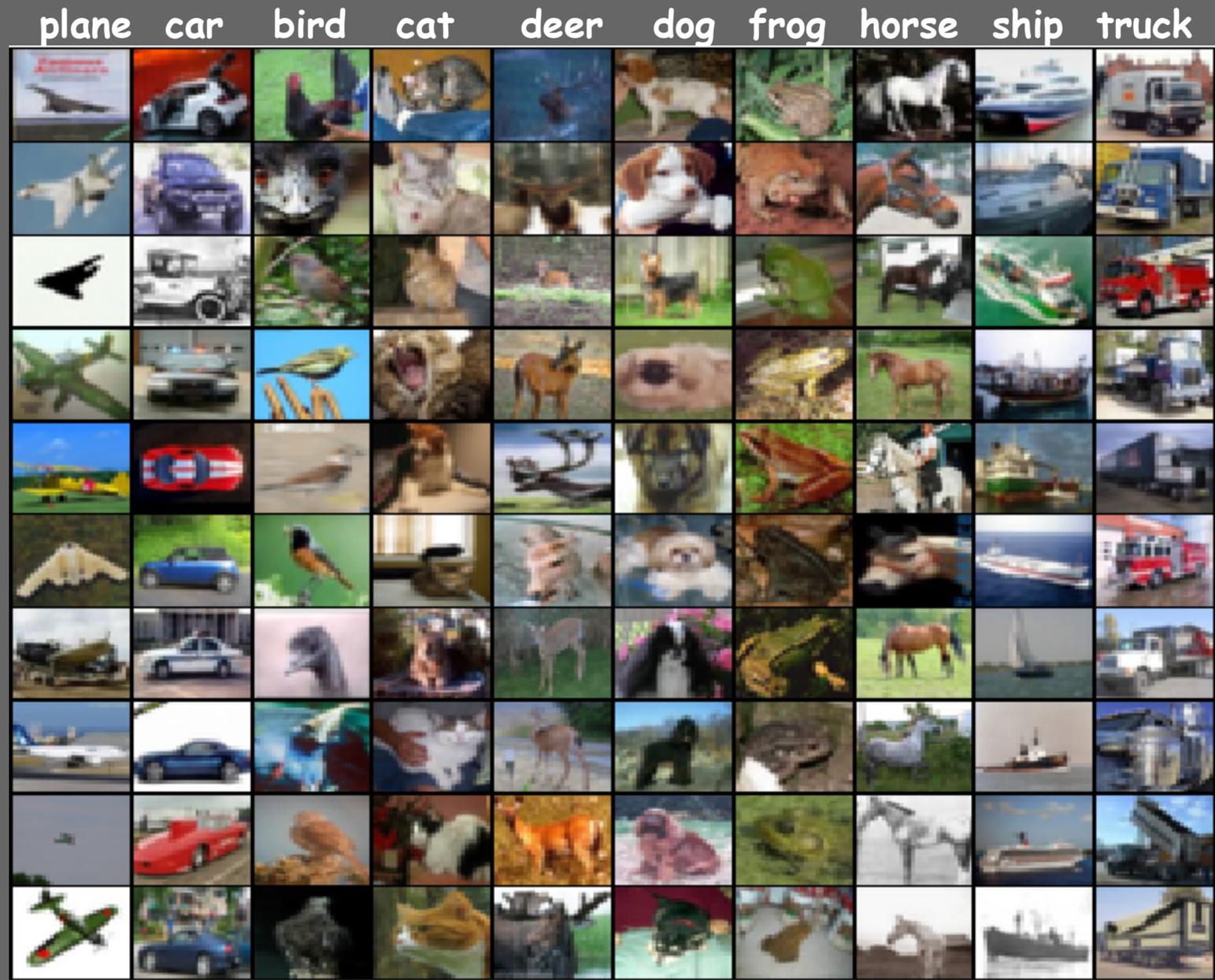
Learned filters: Gabor fit



Learned filters: grouping



RECOGNITION: CIFAR 10 dataset



RECOGNITION: CIFAR 10 dataset

Accuracy

3way RBM - DBN

input -> 9800 - 4096

64.7%

GRBM - DBN*

input - 10000 - 10000

56.6%

3way RBM - DBN

input -> 9800 - 4096 - 384

58.7%

GIST

input - 384

54.7%

* from Krizhevsky 2009

Conclusions

- Model of natural images producing binary features
 - Invariance or robustness to distortions
 - Good for recognition
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 - Easy to integrate with DBN's
- Code and more recent developments available at:
<http://www.cs.toronto.edu/~ranzato>

THANK YOU!