

A Class of Linear Boundary Value Problem for k -regular Functions in Clifford Analysis

Yan Zhang¹

¹ School of Mathematics and Information Science, Beifang University of Nationalities, Yinchuan 750021, P. R. China.
E-mail: yzhangbun@163.com

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Abstract

In this paper, we introduce the linear boundary value problem for k -regular function, and give a unique solution for this problem by integral equation method and fixed-point theorem.

Keywords: k -regular function, Clifford analysis

1. Introduction

The boundary value problem is one of the important aspects in Clifford analysis. This problem on bounded domains has seen great achievements. [Wen, 1991; Huang, 1996; Zhang et al., 2001] have discussed Riemann-Hilbert boundary value problems of regular function on bounded domains. [Li, 2007] characterized boundary value problems of k -regular functions. In this paper, we introduce the *linear* boundary value problem of k -regular function, and give a unique solution to this problem by integral equation method and fixed-point theorem.

Let n be a positive integer, and $\{e_0, e_1, \dots, e_n\}$ be basis for the Euclidean space \mathbb{R}^{n+1} . We denote by \mathcal{A} the 2^n dimensional real Clifford algebra, which is generated by \mathbb{R}^{n+1} ; denote the basis of \mathcal{A} by $e_A = e_{\alpha_1, \alpha_2, \dots, \alpha_h}$, $A = \{\alpha_1, \alpha_2, \dots, \alpha_h\} \subseteq \{1, 2, \dots, n\}$, $1 \leq \alpha_1 < \alpha_2 < \dots < \alpha_h \leq n$. In particular, if $A = \emptyset$, $e_\emptyset = e_0$. So, for an arbitrary $u \in \mathcal{A}$, we have $u = \sum_A u_A e_A$ with $u_A \in \mathbb{R}$. In \mathcal{A} , we have

$$e_i^2 = -1, e_i e_j = -e_j e_i \text{ for } i \neq j, i, j = 1, 2, \dots, n,$$

that is so-called combinative and incommutable multiplication rule of Clifford algebra. For $u \in \mathcal{A}$, we write $u^* = \sum_A (-1)^{\frac{|A|(|A|-1)}{2}} u_A e_A$, $u' = \sum_A (-1)^{\frac{|A|}{2}} u_A e_A$ and $|u|$ for its module, where $|A|$ is the cardinality of the index set A . Define $|u|^2 = \sum_A |u_A|^2$; \bar{u} its conjugate with $\bar{u} = (u^*)'$, where $u^* = \sum_A (-1)^{\frac{|A|(|A|-1)}{2}} u_A e_A$, and $u' = \sum_A (-1)^{|A|} u_A e_A$. For $u, v \in \mathcal{A}$, we have

$$|u + v| \leq |u| + |v|, |uv| \leq 2^n |u| |v|.$$

Let D be a region in \mathbb{R}^{n+1} . For a differentiable function $f : D \rightarrow \mathcal{A}$ with $f(x) = \sum_A f_A(x) e_A$, we say f is a *regular function* if

$$\bar{\partial} f = \sum_{i=0}^n e_i \frac{\partial f}{\partial x_i} = \sum_{i=0}^n \sum_A e_i e_A \frac{\partial f_A}{\partial x_i} = 0,$$

and a *k -regular function* if $\bar{\partial}^k f = 0$, where the operator $\bar{\partial} = \sum_{j=0}^n \frac{\partial}{\partial x_j} e_j$. Let $\Omega \subset \mathbb{R}^{n+1}$ be an unbounded domain with smooth oriented Liapunov boundary $\partial\Omega$, and Ω^c , the complementary set of Ω containing a non-empty open set. We denote the bounded Hölder continuous function on $\partial\Omega$ in order of β ($0 < \beta < 1$) by $H(\partial\Omega, \beta)$. For $f \in H(\partial\Omega, \beta)$, we define its norm by

$$\|f\|_\beta = \sup_{t \in \partial\Omega} |f(t)| + \sup_{t_1 \neq t_2} \frac{|f(t_1) - f(t_2)|}{|t_1 - t_2|}.$$

Then $H(\partial\Omega, \|\cdot\|_\beta)$ is a Banach space. And for $f, g \in H(\partial\Omega, \|\cdot\|_\beta)$, we have

$$\|f + g\|_\beta \leq \|f\|_\beta + \|g\|_\beta, \|fg\|_\beta \leq 2^n \|f\|_\beta \|g\|_\beta.$$

2. Main Result

In what follows, we denote by Ω a non-empty connected open set in \mathbb{R}^{n+1} with smooth oriented Liapunov boundary $\partial\Omega$, and by w_n the area of unit ball in \mathbb{R}^{n+1} . We first give the linear boundary value problem for k -regular function.

Definition 2.1. Let $A(t), B(t), g_l(t) \in H(\partial\Omega, \beta)$, $1 \leq l \leq k$. Write $\Omega^+ = \Omega$, $\Omega^- = \mathbb{R}^{n+1} \setminus \bar{\Omega}$ with $\bar{\Omega} = \Omega \cup \partial\Omega$. If there exists some function ϕ such that

- 1) ϕ is a k -regular function on Ω^\pm ;
- 2)

$$\begin{cases} \phi^+(t)A(t) + \phi^-(t)B(t) = g_1(t) \\ \bar{\partial}\phi^+(t)A(t) + \bar{\partial}\phi^-(t)B(t) = g_2(t) \\ \vdots \\ \bar{\partial}^{k-1}\phi^+(t)A(t) + \bar{\partial}^{k-1}\phi^-(t)B(t) = g_k(t) \end{cases} \tag{1}$$

Then we say ϕ is a solution to the linear boundary problem. And this problem is also called linear boundary problem for k -regular function.

The following lemmas are borrowed from [Li, 2007]:

Lemma 2.1. Let $f(x)$ be a k -regular function on Ω . Then we have

$$f(x) = \sum_{m=0}^{k-1} \frac{1}{m!} x_0^m f_m(x), \tag{2}$$

where $f_m, m = 0, 1, \dots, k - 1$ are regular functions defined on Ω .

Lemma 2.2 Here we give Plemelj equation for regular function:

$$\phi_m^\pm = \pm \frac{1}{2} \varphi_m + \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^{n+1}} m(\tau) \varphi_m(\tau) d_{s_\tau}. \tag{3}$$

where $m(u)$ is the unit vector in $\partial\Omega$'s normal direction, and $\varphi_j \in H(\partial\Omega, \beta), j = 0, 1, \dots, k - 1$. Then ϕ is a regular function on $\mathbb{R}^{n+1} \setminus \partial\Omega$.

The following lemma is borrowed from [Xu et al., 2008]

Lemma 2.3. Let $\phi \in H(\partial\Omega, \beta)$. Define a operator K on $H(\partial\Omega, \beta)$ by

$$(K\phi)(x) = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \phi(\tau) d_{s_\tau} \tag{4}$$

for $x \in \partial\Omega$. Then there exists some $C > 0$ such that $\|K \cdot\| \leq C\| \cdot\|$ on $H(\partial\Omega, \beta)$.

Theorem 2.1. Let $A(t), B(t), g_l(t), (1 \leq l \leq k) \in H(\partial\Omega, \beta)$. If

$$\begin{aligned} \zeta &= 2^n \left[\left(\frac{1}{2} + C \right) (\|A + B\|) + \|1 - B\| \right] \in (0, 1), \\ \|g'_{m+1}\|_\beta &\leq M(1 - \zeta), \end{aligned} \tag{5}$$

where C is in Lemma 2.3, then the solution of the m -th equation in (1) is given by

$$\phi(x) = \sum_{m=0}^{k-1} \frac{1}{m!} x_1^m \phi_m(x)$$

with

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau}$$

for $m = 0, 2, \dots, k - 1$.

Proof. Substituting (2) into (1), we have

$$T \begin{pmatrix} \phi_0^+ \\ \vdots \\ \phi_{k-2}^+ \\ \phi_{k-1}^+ \end{pmatrix} A + T \begin{pmatrix} \phi_0^- \\ \vdots \\ \phi_{k-2}^- \\ \phi_{k-1}^- \end{pmatrix} B = \begin{pmatrix} g_1 \\ \vdots \\ g_{k-1} \\ g_k \end{pmatrix} \tag{6}$$

where

$$T = \begin{pmatrix} 0 & 0 & 0 & \cdots & 1 \\ 0 & 1 & x_1 & \cdots & \frac{1}{(k-2)!} x_1^{k-2} \\ \vdots & \vdots & \vdots & & \\ 1 & x_1 & \frac{1}{2!} x_1^2 & \cdots & \frac{1}{(k-1)!} x_1^{k-1} \end{pmatrix}.$$

We rewrite (6) as

$$\begin{pmatrix} \phi_0^+ & A \\ \vdots & \vdots \\ \phi_{k-2}^+ & A \\ \phi_{k-1}^+ & A \end{pmatrix} + \begin{pmatrix} \phi_0^+ & B \\ \vdots & \vdots \\ \phi_{k-2}^+ & B \\ \phi_{k-1}^+ & B \end{pmatrix} = \begin{pmatrix} g'_1 \\ \vdots \\ g'_{k-1} \\ g'_k \end{pmatrix} \text{ with } \begin{pmatrix} g'_1 \\ \vdots \\ g'_{k-1} \\ g'_k \end{pmatrix} = T^{-1} \begin{pmatrix} g_1 \\ \vdots \\ g_{k-1} \\ g_k \end{pmatrix},$$

which is equivalent to

$$\begin{cases} \phi_0^+ A + \phi_0^- B = g'_1 \\ \phi_1^+ A + \phi_1^- B = g'_2 \\ \vdots \\ \phi_{k-1}^+ A + \phi_{k-1}^- B = g'_k, \end{cases} \tag{7}$$

herein ϕ_m is a regular function given by

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau} \tag{8}$$

for $m = 0, \dots, k - 1$. Next, to finish the proof, we only need to prove that ϕ_m ($0 \leq m \leq k - 1$) given by (8) are solutions to (7). By substituting (3) into (7), we have

$$\left(\frac{1}{2}\varphi_m + K\varphi_m\right)A + \left(-\frac{1}{2}\right)\varphi_m + K\varphi_m B = g'_{m+1} \quad m = 0, \dots, k - 1. \tag{9}$$

Write

$$L\phi_m = \left(\frac{1}{2}\varphi_m + K\varphi_m\right)(A + B) + \varphi_m(1 - B) - g'_{m+1},$$

then (9) can be rewritten as $L\phi_m = \phi_m$. Let $T = \{\varphi | \varphi \in H(\partial\Omega, \beta), \|\varphi\|_\beta \leq M\}$. Then T is a closed subspace of $H(\partial\Omega, \beta)$. Since

$$\begin{aligned} \|L\varphi_m\|_\beta &= \left\| \left(\frac{1}{2}\varphi_m + K\varphi_m\right)(A + B) + (1 - B)\varphi_m - g'_{m+1} \right\| \\ &\leq 2^n \left[\left(\frac{1}{2} + C\right)(\|A + B\|) + \|1 - B\| \right] \|\varphi_m\| + \|g'_{m+1}\| \\ &\leq \zeta \|\varphi_m\| + \|g'_{m+1}\| \\ &\leq M, \end{aligned} \tag{10}$$

F is a map on T . For $\phi'_m, \phi''_m \in T$, we have

$$\|L\phi'_m - L\phi''_m\| \leq \zeta \|\phi'_m - \phi''_m\|_\beta,$$

with $0 < \zeta < 1$, and thus L is a compression map on T . So, there is an unique fixed φ_m such that $L\varphi_m = \varphi_m$ by fixed point theorem, which implies that

$$\phi_m = \frac{1}{w_n} \int_{\partial\Omega} \frac{\overline{\tau - x}}{|\tau - x|^n} m(\tau) \varphi_m(\tau) d_{s_\tau}$$

is unique solution for the m -th equation in (7). This gives the proof.

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