

Solution of a Class of Differential Equation with Variable Coefficients

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Abstract

In this paper, we obtain the formula of solution to the initial value problem for a hyperbolic partial differential equation with variable coefficient which is the modification of the famous D' Alembert formula.

Keywords: Differential equation with variable coefficient; Solution; D' Alembert formula

1. Introduction

The exact solutions are always not easy to find for differential equations, especially for differential equations with variable coefficients, nonlinear differential equations. Luckily¹, Euler equation as a ordinary differential equation with variable coefficients

$$a_k x^k \frac{d^k y}{dx^k} + a_{k-1} x^{k-1} \frac{d^{k-1} y}{dx^{k-1}} + \dots + a_1 x \frac{dy}{dx} + a_0 y = 0$$

can be solved by variable transformation $y = \ln x$ which satisfies

$$x^k \frac{d^k}{dx^k} = k(k-1) \dots \frac{d^k}{dy^k}.$$

Gained enlightenment from Euler equation, the famous Black-Scholes equation²

$$\partial_t V + \sigma^2 S^2 \cdot \partial_s^2 V + rS \cdot \partial_s V - rV = 0,$$

was solved after changing it into heat conduct equation $\partial_t V - \sigma^2 \partial_x^2 V = 0$ by variable transformation $T = \ln S$ ³. In this paper, we study the solutions of the following differential equation with variable coefficient:

$$\partial_t^2 u - a^2 (x^2 \partial_x^2 + x \partial_x) u = f(t, x) \quad (1)$$

which is similar to the Black-Scholes equation.

When $x \neq 0$, (1) is hyperbolic (since $\Delta = a^2 x^2 > 0, \forall x \neq 0$), the initial value problem of which includes two cases⁴:

$$\begin{cases} \partial_t^2 u - a^2 (x^2 \partial_x^2 + x \partial_x) u = f(t, x), & 0 < x < \infty, t > 0, \\ u(0, x) = \phi(x), & 0 < x < \infty, \\ u_t(0, x) = \psi(x), & 0 < x < \infty, \end{cases} \quad (2)$$

and

¹ See for example the book by Wang G X., Zhou Z M, Zhu SM (2007).

² Black F, Scholes, M (1973) proposed this financial model when studying the pricing of options and corporate liabilities.

³ Consult the book by Jiang L S (2008) for the detail.

⁴ On the degenerate line $x = 0$, no boundary conditions are necessary to posed on it. Consult the book by E. DiBenedetto (1993).

$$\begin{cases} \partial_t^2 u - a^2(x^2 \partial_x^2 + x \partial_x)u = f(t, x), & -\infty < x < 0, t > 0, \\ u(0, x) = \phi(x), & -\infty < x < 0, \\ u_t(0, x) = \psi(x), & -\infty < x < 0. \end{cases} \tag{3}$$

When $x = 0$, (1) degenerate to 2-order ordinary differential equation, the initial value problem of which is:

$$\frac{d^2 u}{dt^2} = f(t), \quad u(0) = u_0, \quad \frac{du}{dt}(0) = u_1. \tag{4}$$

By the variable transformation $y = \ln x$, the hyperbolic equation with variable coefficients $\partial_{tt}u - a^2(x^2 \partial_{xx} + x \partial_x)u = 0$ can be convert into the string vibrating equation $\partial_{tt}u - a^2 \partial_{yy}u = 0$. Thus, the solution of (2), (3) can be found by applying the famous D' Alembert formula of the string vibrating equation $\partial_{tt}u - a^2 \partial_{yy}u = 0$.

2. Solutions of the Initial Value Problem

Let's recall D' Alembert formula first which is exact solution for initial value problem of string vibrating equation (see i.g. J. Smoller (1994)):

Lemma 1. If $\phi \in C^2(-\infty, \infty)$, $\psi \in C^1(-\infty, \infty)$ and $f \in C^1[(-\infty, \infty) \times (0, \infty)]$. The initial value problem

$$\begin{cases} \partial_t^2 u - a^2 \partial_x^2 u = f(t, x), & -\infty < x < \infty, t > 0, \\ u(0, x) = \phi(x), & -\infty < x < \infty, \\ \partial_t u(0, x) = \psi(x), & -\infty < x < \infty \end{cases}$$

has the unique solution

$$u(t, x) = \frac{\phi(x - at) + \phi(x + at)}{2} + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi + \frac{1}{2a} \int_0^t \int_{x-a(t-\tau)}^{x+a(t-\tau)} f(\xi, \tau) d\xi d\tau. \tag{5}$$

Based on (5), we can establish the solution of (2) as follows:

Theorem 2. If $\phi \in C^2(0, \infty)$, $\psi \in C^1(0, \infty)$ and $f \in C^1[(0, \infty) \times (0, \infty)]$. Then the initial value problem (2) has unique solution

$$u(t, x) = \frac{\phi(e^{\ln x - at}) + \phi(e^{\ln x + at})}{2} + \frac{1}{2a} \int_{\ln x - at}^{\ln x + at} \psi(e^\xi) d\xi + \frac{1}{2a} \int_0^t \int_{\ln x - a(t-\tau)}^{\ln x + a(t-\tau)} f(e^\xi, \tau) d\xi d\tau. \tag{6}$$

Proof. By the variable transformation $y = \ln x$, we obtain

$$x \partial_x = \partial_y, \quad x^2 \partial_x^2 = \partial_y^2 - \partial_y.$$

Applying the above formula to

$$\partial_{tt}u - a^2(x^2 \partial_x^2 + x \partial_x)u = 0, \quad t > 0, \quad 0 < x < \infty,$$

we obtain

$$\partial_{tt}u - a^2 \partial_{yy}u = 0, \quad t > 0, \quad -\infty < y < \infty.$$

Thus, initial value problem (2) is converted to

$$\begin{cases} \partial_t^2 u - a^2 \partial_y^2 u = f(t, e^y), & -\infty < y < \infty, t > 0, \\ u(0, y) = \phi(e^y), & -\infty < y < \infty, \\ u_t(0, y) = \psi(e^y), & -\infty < y < \infty. \end{cases} \tag{7}$$

Applying the formula (5) to (7), we obtain

$$u(t, y) = \frac{\phi(e^{y-at}) + \phi(e^{y+at})}{2} + \frac{1}{2a} \int_{y-at}^{y+at} \psi(e^\xi) d\xi + \frac{1}{2a} \int_0^t \int_{y-a(t-\tau)}^{y+a(t-\tau)} f(e^\xi, \tau) d\xi d\tau.$$

Since $y = \ln x$, finally we obtain the solution of (2)

$$u(t, x) = \frac{\phi(e^{\ln x-at}) + \phi(e^{\ln x+at})}{2} + \frac{1}{2a} \int_{\ln x-at}^{\ln x+at} \psi(e^\xi) d\xi + \frac{1}{2a} \int_0^t \int_{\ln x-a(t-\tau)}^{\ln x+a(t-\tau)} f(e^\xi, \tau) d\xi d\tau. \quad \square$$

In order to find the solution of (3), we'll establish the relation between (2) and (3) first. To this end, apply transformation $y = -x$ to (3). Then, we have

$$x\partial_x = y\partial_y, \quad x^2\partial_x^2 = y^2\partial_y^2$$

which implies that (3) can be converted into

$$\begin{cases} \partial_t^2 u - a^2(y^2\partial_x^2 + y\partial_x)u = f(t, -y), & 0 < y < \infty, t > 0, \\ u(0, y) = \phi(-y), & 0 < y < \infty, \\ u_t(0, y) = \psi(-y), & 0 < y < \infty. \end{cases} \quad (8)$$

Applying (6) to (8), obtain

$$u(t, y) = \frac{\phi(-e^{\ln y-at}) + \phi(-e^{\ln y+at})}{2} + \frac{1}{2a} \int_{\ln y-at}^{\ln y+at} \psi(-e^\xi) d\xi + \frac{1}{2a} \int_0^t \int_{\ln y-a(t-\tau)}^{\ln y+a(t-\tau)} f(-e^\xi, \tau) d\xi d\tau.$$

Put back $y = -x$ into the above equation, we obtain the formula which we desired:

Theorem 3. If $\phi \in C^2(-\infty, 0)$, $\psi \in C^1(-\infty, 0)$ and $f \in C^1[(0, \infty) \times (-\infty, 0)]$. Then the initial value problem (1.3) has unique solution

$$u(t, x) = \frac{\phi(-e^{\ln(-x)-at}) + \phi(-e^{\ln(-x)+at})}{2} + \frac{1}{2a} \int_{\ln(-x)-at}^{\ln(-x)+at} \psi(-e^\xi) d\xi + \frac{1}{2a} \int_0^t \int_{\ln(-x)-a(t-\tau)}^{\ln(-x)+a(t-\tau)} f(-e^\xi, \tau) d\xi d\tau. \quad (9)$$

□

Finally, (4) is the initial value problem of second order ordinary differential equation, its solution is as follows:

$$u(t) = u_1 t + u_0 + \int_0^t \int_0^\xi f(\eta) d\eta d\xi.$$

3. Applications

Example 4. Find the solution of the initial value problem:

$$\begin{cases} u_{tt} - a^2(x^2 u_{xx} + x u_x) = t + x, & 0 < x < \infty, t > 0, \\ u(0, x) = x, & 0 < x < \infty, \\ u_t(0, x) = \ln x, & 0 < x < \infty. \end{cases} \quad (10)$$

Let $\phi(x) = x$, $\psi(x) = \ln x$, $f(t, x) = t + x$. Apply the formula (6) to (10), we obtain:

$$u(t, x) = \frac{e^{\ln x+at} + e^{\ln x-at}}{2} + t \cdot \ln x + \frac{1}{6} t^3 + \frac{x}{2a^2} (e^{at} + e^{-at} - 2). \quad \square$$

Example 5. Find the solution of the initial value problem:

$$\begin{cases} u_{tt} - a^2(x^2 u_{xx} + x u_x) = t + x, & -\infty < x < 0, t > 0, \\ u(0, x) = \sin x, & -\infty < x < 0, \\ u_t(0, x) = x, & -\infty < x < 0. \end{cases} \quad (11)$$

Let $\phi(x) = \sin x$, $\psi(x) = x$, $f(t, x) = t + x$. Apply formula (9) to (11), we obtain:

$$u(t, x) = -\frac{\sin(e^{\ln(-x)+at}) + \sin(e^{\ln(-x)-at})}{2} - \frac{e^{\ln(-x)+at} - e^{\ln(-x)-at}}{2a} + \frac{t^3}{6} + \frac{x(e^{at} + e^{-at} - 2)}{2a^2}. \quad \square$$

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