

Physics for Data Structures condensesses and tags items accordingly

Physics of Classification - Data Tagging

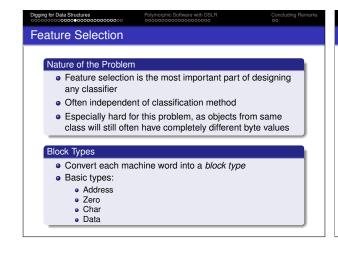
Supervised Learning
Inference engine is trained on labeled data with a set of given classes. Easier, more effective, simpler to validate. Labeled data not always possible.

Unsupervised Learning
Inference engine is given data set and asked to generate a set of classes. Engine finds number of distinct classes and tags items accordingly

Types of Classification - Underlying Learning Method

• Generative - Learning machine attempts to learn an underlying probability distribution. This is helpful because probabilistic methods such as expectation maximization (or its Bayesian counterpart maximum a posteriori) become available to use.

• Discriminative - Learning machine attempts to learn the best way to determine class boundaries. This is often more specialized and data efficient at the cost of flexibility.



Polymorphe Software with DBLH Concluding Remarks

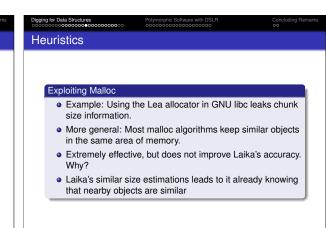
Feature Selection

Atom Types

Classes are represented as vector of atoms
Atoms are a collection of blocks, so we need to identify atoms from block streams
Basic atom types:
Pointer
Zero
String
Integer

Looks like there's some relation between atom and block types...
A block type is an atomic type with some error. This can be observed by examining P(blocktype|atomictype)

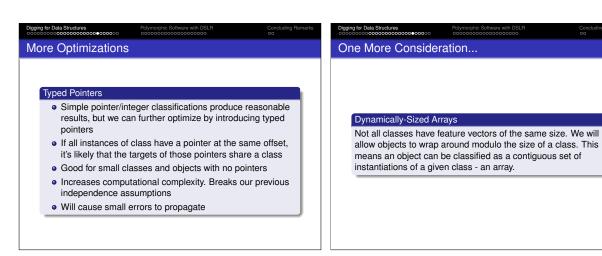
Digging for Data Structures	Polymorphic Software with DSLR	Concluding Remark	
Finding Data Structures			
Basic Process			
Scan through me	emory and identify pointers		
_	 Tentatively estimate the start position of objects using locations from pointers 		
Find the end pos clustering	Find the end position using estimation done during clustering		
The rest of the bl as random noise	The rest of the block past the end of the object is classified as random noise		
Introduce a rando	om atomic type to handle this	s noise	

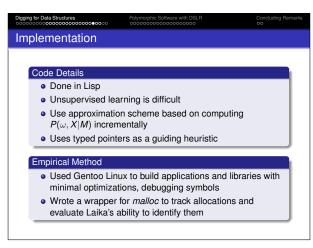


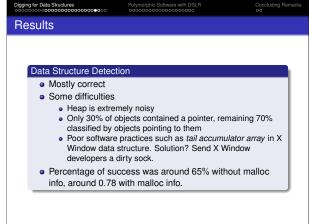
Polymorphic Software with DSLR cools and Model
 The Ith machine word of memory image M is notated M_I.
 The kth atomic type of class j is ω_{jk}.
 X is the input list, with X_i indicating the position ith object in X.
 We want to maximize the most likely objects and classes given a memory image. An equation for this can be obtained with the following steps:

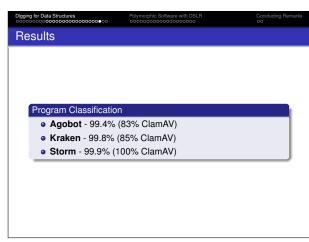
 Bayesian approach means MAP. We can get this from Bayes' rule as P(Θ|X) = P(X|Θ)P(Θ).
 Plugging in the values specific to this problem we get P(ω, X|M) = P(M|ω,X)P(ω,X)/P(X|ω)P(ω).
 Applying the chain rule to the class and object joint distribution, we obtain P(ω, X|M) = P(M|ω,X)P(X|ω)P(ω)/P(M).

Polymorphic Software with DSLR concluding Remarks consequences of consequence

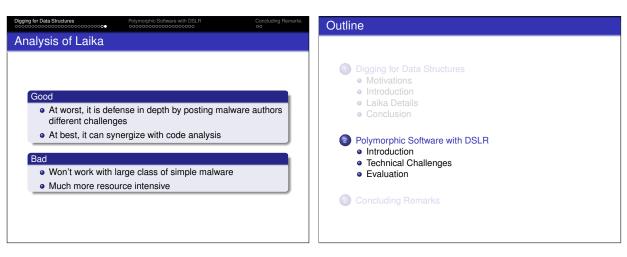


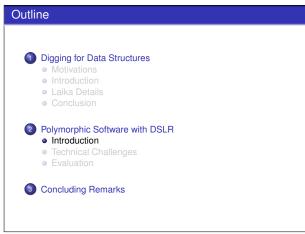


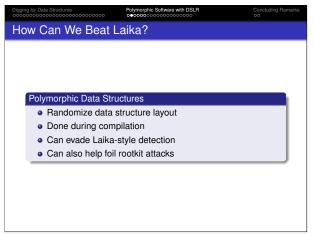


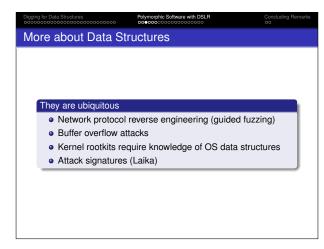


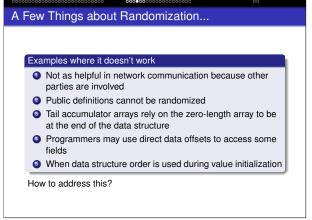


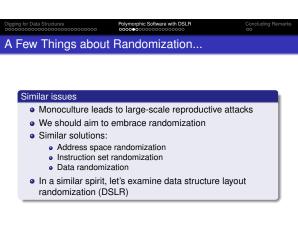


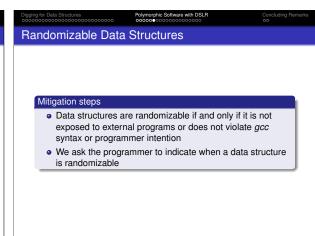




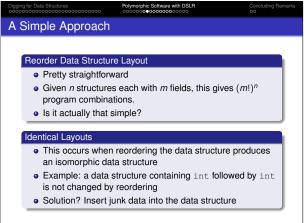


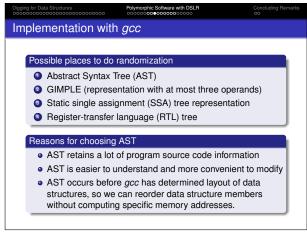


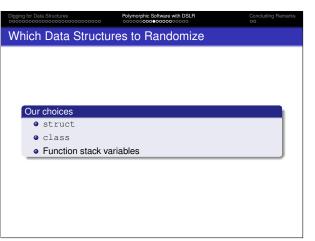


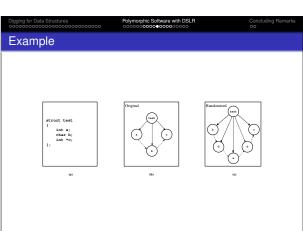


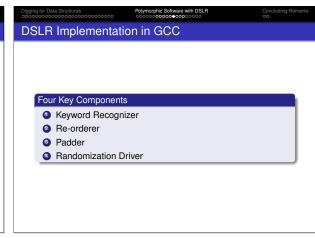


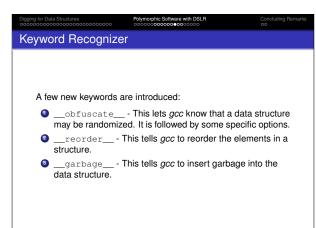


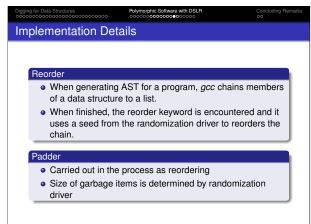


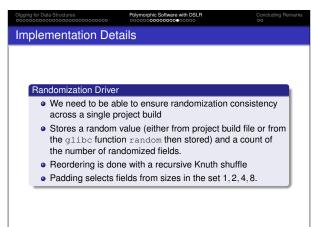


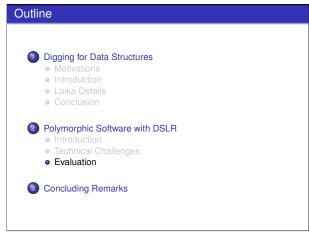


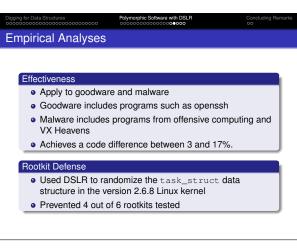


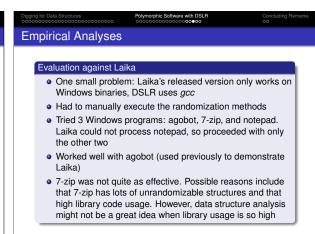




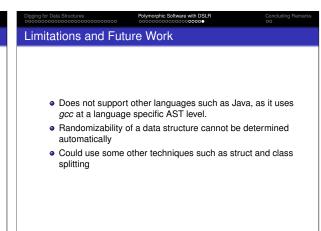


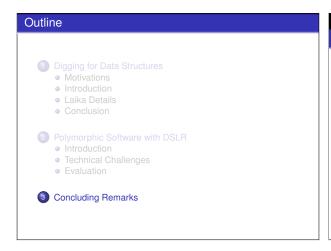


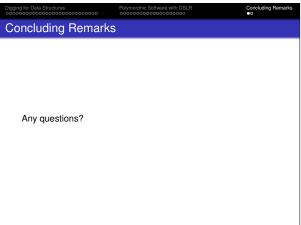




Pelymorphe Solware with DSLR Concluding Remarks Con







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