Improved Ratio Type Estimator Using Two Auxiliary Variables under Second Order Approximation

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Abstract

In this paper, we have proposed a new Ratio Type Estimator using auxiliary information on two auxiliary variables based on Simple random sampling without replacement (SRSWOR). The proposed estimator is found to be more efficient than the estimators constructed by Olkin (1958), Singh (1965), Lu (2010) and Singh and Kumar (2012) in terms of second order mean square error.

Keywords: simple random sampling, population mean, study variable, auxiliary variable, ratio type estimator, product estimator, Bias and MSE.

1. Introduction

In sampling survey, the use of auxiliary information is always useful in considerable reduction of the MSE of a ratio type estimator. Therefore, many authors suggested estimators using some known population parameters of an auxiliary variable. Hartley-Ross (1954), Quenouille's (1956) and Olkin (1958) have considered the problem of estimating the mean of a survey variable when auxiliary variables are made available. Jhajj and Srivastava (1983), Singh et al.(1995),

Upadhyaya and Singh (1999), Singh and Tailor (2003), Kadilar and Cingi (2006), Khoshnevisan et al. (2007), Singh et al. (2007), Singh and Kumar (2011,), etc. suggested estimators in simple random sampling using auxiliary variable.

Moreover, when two auxiliary variables are present Singh (1965,1967) and Perri(2007) suggested some ratio -cum -product type estimators. Most of these authors discussed the properties of estimators along with their first order bias and MSE. Hossain et al. (2006), Sharma et al. (2013a, b) studied the properties of some estimators under second order approximation. In this paper, we have suggested an estimator using auxiliary information in simple random sampling and compared with some existing estimators under second order of approximation when information on two auxiliary variables are available.

Let $U= (U_1 ,U_2 , U_3, …..,U_i, ….U_N)$ denotes a finite population of distinct and identifiable units. For estimating the population mean $\overline{Y}$ of a study variable Y, let us consider X and Z are the two auxiliary variable that are correlated with study variable Y, taking the corresponding values of the units. Let a sample of size n be drawn from this population using simple random sampling without replacement (SRSWOR) and y_i , x_i and z_i (i=1,2,…..n) are the values of the study variable and auxiliary variables respectively for the i-th units of the sample.

When the information on two auxiliary variables are available Singh (1965,1967) proposed some ratio-cum-product estimators in simple random sampling without replacement to estimate the population mean $\overline{Y}$ of the study variable y, generalized version of one of these estimators is given by,

$$t_1 = \overline{y}\left(\frac{\overline{X}}{\overline{x}}\right)^{\alpha_1}\left(\frac{\overline{Z}}{\overline{z}}\right)^{\alpha_2} \tag{1.1}$$

where α_1 and α_2 are suitably chosen scalars such that the mean square error of t_1 is minimum.

and $\bar{y} = \dfrac{1}{n} \sum\limits_{i=1}^{n} y_i$, $\bar{x} = \dfrac{1}{n} \sum\limits_{i=1}^{n} x_i$ and $\bar{z} = \dfrac{1}{n} \sum\limits_{i=1}^{n} z_i$,

Olkin(1958) proposed an estimator t_2 as-

$$t_2 = \bar{y}\left[\lambda_1 \frac{\bar{X}}{\bar{x}} + \lambda_2 \frac{\bar{Z}}{\bar{z}} \right] \tag{1.2}$$

where, λ_1 and λ_2 are the weights that satisfy the condition $\lambda_1 + \lambda_2 = 1$

Lu (2010) proposed multivariate ratio estimator using information on two auxiliary variables as-

$$t_3 = \bar{y}\left[\frac{w_1\bar{X}_1 + w_2\bar{X}_2}{w_1\bar{x}_1 + w_2\bar{x}_2} \right]^{\alpha} \tag{1.3}$$

where, w_1 and w_2 are weights that satisfy the condition: $w_1 + w_2 = 1$.

Singh and Kumar (2012) proposed exponential ratio-cum-product estimator. Generalized form of this estimator is given by

$$t_4 = \bar{y}\exp\left[\frac{\bar{X} - \bar{x}}{\bar{X} + \bar{x}} \right]^{\beta_1} \exp\left[\frac{\bar{Z} - \bar{z}}{\bar{Z} + \bar{z}} \right]^{\beta_2} \tag{1.4}$$

where β_1 and β_2 are constants such that the MSE of estimator t_4 is minimise.

<u>Theorem1.1</u> Let $e_0 = \dfrac{\bar{y} - \bar{Y}}{\bar{Y}}$, $e_1 = \dfrac{\bar{x} - \bar{X}}{\bar{X}}$ and $e_2 = \dfrac{\bar{z} - \bar{Z}}{\bar{Z}}$

then $E(e_0) = E(e_1) = E(e_2) = 0$ and variances and co-variances are as follows:

(i) $V(e_0) = E\{(e_0)^2\} = \dfrac{L_1 C_{200}}{\bar{Y}^2} = V_{200}$

(ii) $V(e_1) = E\{(e_1)^2\} = \dfrac{L_1 C_{020}}{\bar{X}^2} = V_{020}$

(iii) $V(e_1) = E\{(e_2)^2\} = \dfrac{L_1 C_{002}}{\bar{Z}^2} = V_{002}$

(iv) $COV(e_0, e_1) = E\{(e_0 e_1)\} = \dfrac{L_1 C_{110}}{\bar{X}\bar{Y}} = V_{110}$

(v) $COV(e_1, e_2) = E\{(e_1 e_2)\} = \dfrac{L_1 C_{011}}{\overline{X}\overline{Z}} = V_{011}$

(vi) $COV(e_0, e_2) = E\{(e_0 e_2)\} = \dfrac{L_1 C_{101}}{\overline{Y}\overline{Z}} = V_{101}$

(vii) $E\{(e_0{}^2 e_1)\} = \dfrac{L_2 C_{210}}{\overline{Y}^2 \overline{X}} = V_{210}$

(viii) $E\{(e_0{}^2 e_2)\} = \dfrac{L_2 C_{201}}{\overline{Y}^2 \overline{Z}} = V_{201}$

(ix) $E\{(e_1{}^2 e_2)\} = \dfrac{L_2 C_{021}}{\overline{X}^2 \overline{Z}} = V_{021}$

(x) $E\{(e_0 e_1^2)\} = \dfrac{L_2 C_{120}}{\overline{Y}\overline{X}^2} = V_{120}$

(xi) $E\{(e_1 e_2^2)\} = \dfrac{L_2 C_{012}}{\overline{X}\overline{Z}^2} = V_{012}$

(xii) $E\{(e_0 e_2^2)\} = \dfrac{L_2 C_{102}}{\overline{Y}\overline{Z}^2} = V_{102}$

(xiii) $E\{(e_1{}^3)\} = \dfrac{L_2 C_{030}}{\overline{X}^3} = V_{030}$

(xiv) $E(e_1{}^3 e_2) = \dfrac{L_3 C_{031} + 3 L_4 C_{020} C_{011}}{\overline{X}^3 \overline{Z}} = V_{031}$

(xv) $E(e_1 e_2^3) = \dfrac{L_3 C_{013} + 3 L_4 C_{002} C_{011}}{\overline{X}\overline{Z}^3} = V_{013}$

(xvi) $E(e_0 e_1{}^3) = \dfrac{L_3 C_{130} + 3 L_4 C_{020} C_{110}}{\overline{Y}\overline{X}^3} = V_{130}$

where, $L_1 = \dfrac{(N-n)}{(N-1)}\dfrac{1}{n}$, $\qquad L_2 = \dfrac{(N-n))(N-2n)}{(N-1)(N-2)}\dfrac{1}{n^2}$

$$L_3 = \frac{(N-n))(N^2+N-6nN+6n^2)}{(N-1)(N-2)(N-3)}\frac{1}{n^3}, \quad L_4 = \frac{N(N-n))(N-n-1)(n-1)}{(N-1)(N-2)(N-3)}\frac{1}{n^3}$$

And $\qquad Cpqr = \displaystyle\sum_{i=1}^{N} (Xi - \overline{X})^p (Y_i - \overline{Y})^q (Z_i - \overline{Z})^r$

This theorem will be used to obtain MSE expressions of estimators considered here. Proof of this theorem is straight forward by using SRSWOR (see Sukhatme and Sukhatme (1970)).

2. First Order Biases and Mean Squared Errors

The expression of the biases of the estimators t_1, t_2 t_3 and t_4 to the first order of approximation are respectively, written as

$$\text{Bias}(t_1) = \overline{Y}\left[-\alpha_1 V_{110} + \alpha_2 V_{102} + R_1 V_{020} + S_1 V_{002} + \alpha_1\alpha_2 V_{011}\right] \tag{2.1}$$

where , $R_1 = \dfrac{\alpha_1(\alpha_1+1)}{2}$ $\quad S_1 = \dfrac{\alpha_2(\alpha_2+1)}{2}$.

$$\text{Bias}(t_2) = \overline{Y}\left[-w_1 V_{110} - w_2 V_{101} + w_1 V_{020} + w_2 V_{002} + \alpha_1\alpha_2 V_{011}\right] \tag{2.2}$$

$$\text{Bias}(t_3) = \overline{Y}\left[-\alpha\lambda\left(w_1\overline{X}_1 V_{110} - w_2 V_{101}\right)\right.$$

$$\left. + \lambda^2\alpha\frac{(\alpha+1)}{2}\left(w_1^2\overline{X}_1^2 V_{020} + w_2^2\overline{X}_2^2 V_{002} + 2w_1 w_1\overline{X}_1\overline{X}_2 V_{011}\right)\right] \tag{2.3}$$

where, $\lambda = \dfrac{1}{w_1\overline{X}_1 + w_2\overline{X}_2}$

$$\text{Bias}(t_4) = \overline{Y}\left[-\frac{\beta_1}{2}V_{110} - \frac{\beta_2}{2}V_{101} + V_{020}\left(\frac{\beta_1}{4} + \frac{\beta_1^2}{8}\right) + \left(\frac{\beta_2}{4} + \frac{\beta_2^2}{8}\right)V_{002}\right] \tag{2.4}$$

Expressions for the MSE of the estimators t_1, t_2, t_3 and t_4 to the first order of approximation are respectively, given by

$$\text{MSE}(t_1) = \overline{Y}^2\left[V_{200} + \alpha_1^{\,2}V_{020} + \alpha_2^2 V_{002} - 2\alpha_1 V_{110} - 2\alpha_2 V_{101} + 2\alpha_1\alpha_2 V_{011}\right] \tag{2.5}$$

The MSE of the estimator t_1 is minimized for

$$\alpha_1^* = \left[\frac{\rho_{yx} - \rho_{yz}\rho_{xz}}{1 - \rho_{xz}^2}\right]\sqrt{\frac{V_{200}}{V_{020}}} \tag{2.6}$$

And

$$\alpha_1^* = \left[\frac{\rho_{yz} - \rho_{yx}\rho_{xz}}{1 - \rho_{xz}^2}\right]\sqrt{\frac{V_{200}}{V_{002}}} \tag{2.7}$$

where α_1^* and α_2^* are, respectively, partial regression coefficients of y on x and of y on z in simple random sampling.

$$\text{MSE}(t_2) = \overline{Y}^2\left[V_{200} + \lambda_1^{\,2}V_{020} + \lambda_2^2 V_{002} - 2\lambda_1 V_{110} - 2\lambda_2 V_{101} + 2\lambda_1\lambda_2 V_{011}\right] \tag{2.8}$$

The MSE of the estimator t_2 is minimum for

$$\lambda_1^* = \frac{V_{002} - V_{101} + V_{110} - V_{012}}{V_{020} + V_{002} - 2V_{012}} \quad \text{and} \quad \lambda_2^* = 1 - \lambda_1^* \tag{2.9}$$

$$\text{MSE}(t_3) = \overline{Y}^2\left[V_{200} + \alpha^2\lambda^2\left(w_1^2\overline{X}_1^2 V_{020} + w_2^2\overline{X}_2^2 V_{002} + 2w_1 w_2 \overline{X}_1\overline{X}_2 V_{011}\right)\right.$$

$$\left. - 2\alpha\lambda\left(w_1\overline{X}_1 V_{110} + w_2\overline{X}_2 V_{101}\right]\right. \tag{2.10}$$

Differentiating (2.10) with respect to w_1 and w_2 partially, we get the optimum values of w_1 and w_2 respectively as

$$w_1^* = \frac{\overline{X}_1 V_{110} - \overline{X}_2 V_{101} + \overline{X}_2^2 V_{002} - \overline{X}_1\overline{X}_2 V_{011}}{\overline{X}_1^2 V_{020} + \alpha\lambda\overline{X}_2^2 V_{002} - 2\overline{X}_1\overline{X}_2 V_{011}} \quad \text{and} \quad w_2^* = 1 - w_1^* \tag{2.11}$$

For optimum value of $w_1 = w_1^*$ and $w_2 = w_2^*$, MSE of the estimator t_3 is minimum.

$$\text{MSE}(t_4) = \overline{Y}^2 \left[V_{200} + \frac{\beta_1^2}{4} V_{020} + \frac{\beta_2^2}{4} V_{002} - \beta_1 V_{110} - \beta_2 V_{101} + \frac{\beta_1 \beta_2}{2} V_{011} \right] \qquad (2.12)$$

On differentiating (2.12) with respect to β_1 and β_2 respectively, we get the optimum values of

β_1 and β_2 as

$$\beta_1^* = \frac{2 \left(V_{110} V_{002} - V_{101} V_{011} \right)}{\left(V_{002} V_{020} - V_{011}^2 \right)} \qquad (2.13)$$

and

$$\beta_2^* = \frac{2 \left(V_{020} V_{101} - V_{110} V_{011} \right)}{\left(V_{002} V_{020} - V_{011}^2 \right)} \qquad (2.14)$$

Estimators t_1, t_2 t_3 and t_4 at their respective optimum values attains MSE values which are equal to the MSE of regression estimator for two auxiliary variables.

3.   Proposed Estimator

When auxiliary information on two auxiliary variables are known, we propose an estimator t_5 as

$$t_5 = \overline{y} \left[k_1 \left\{ \frac{c\overline{X} - d\overline{x}}{(c-d)\overline{\overline{X}}} \right\}^{\delta_1} + k_2 \left\{ 2 - \left(\frac{\overline{z}}{\overline{\overline{Z}}} \right)^{\delta_2} \right\} \right] \qquad (3.1)$$

where d and c are either real numbers or a function of the known parameters associated with auxiliary information . k_1 and k_2 are constants to be determined such that the MSE of estimator t_5 is minimum under the condition that $k_1 + k_2 = 1$ and δ_1 and δ_2 are integers and can take values -1, 0 and +1 .

Expressing the estimator t_5 in terms of e's we have

$$t_5 = \overline{Y}\left[k_1(1-\eta_1 e_1)^{\delta_1} + k_2\left\{2-(1+e_2)^{\delta_2}\right\}\right]$$ (3.2)

where, $\eta_1 = \dfrac{d}{c-d}$.

We assume that $|\eta_1 e_1| < 1$ so that $(1-\eta_1 e_1)^{\delta_1}$ are expandable. Expanding the right hand side of (3.2), and neglecting terms of e's having power greater than two we have

$$(t_5 - \overline{Y}) = \overline{Y}\left[-k_1\eta_1\delta_1 e_0 e_1 - k_2\delta_2 e_0 e_2 + k_1 M_1 e_1^2 - k_2 N_1 e_2^2 + \alpha_1\alpha_2 e_1 e_2\right]$$ (3.3)

Taking expectation on both sides we get bias of estimator t_5, to the first degree of approximation as

$$\text{Bias}(t_5) = \overline{Y}\left[-k_1\eta_1\delta_1 V_{110} - k_2\delta_2 V_{101} + k_1 M_1 V_{020} - k_2 N_1 V_{002} + \alpha_1\alpha_2 V_{011}\right]$$ (3.4)

where,

$$M_1 = \frac{\delta_1(\delta_1-1)}{2}\eta_1^2, \qquad N_1 = \frac{\delta_2(\delta_2-1)}{2}.$$

Squaring both sides of (3.3) and neglecting terms of e's having power greater than two we have

$$(t_5 - \overline{Y})^2 = \overline{Y}\left[e_0^2 + k_1^2\eta_1^2\delta_1^2 e_1^2 + k_2^2\delta_2^2 e_2^2 - 2k_1\eta_1\delta_1 e_0 e_1 - 2k_2\delta_2 e_0 e_2 + 2k_1 k_2\delta_1\delta_2\eta_1 e_1 e_2\right]$$ (3.5)

Taking expectation on both sides of (3.5) and using theorem 1.1, we get the MSE of t_5 up to first degree of approximation as

$$\text{MSE}(t_5) = \overline{Y}^2\left[V_{200} + k_1^2\delta_1^2\eta_1^2 V_{020} + k_2^2\delta_2^2 V_{002} - 2k_1\delta_1\eta_1 V_{110} - 2k_2\delta_2 V_{101} + 2k_1 k_2\delta_1\delta_2\eta_1 V_{011}\right]$$ (3.6)

Differentiating (3.6) with respect to k_1 and k_2 partially, equating them to zero and after simplification, we get the optimum values of k_1 and k_2 respectively, as

$$k_1^* = \frac{\delta_1\eta_1 V_{110} + \delta_2^2 V_{002} - \delta_2 V_{102} - \delta_1\delta_2\eta_1 V_{011}}{\delta_1^2\eta_1^2 V_{110} + \delta_2^2 V_{002} - 2\delta_1\delta_2\eta_1 V_{011}} \quad , \quad k_2^* = 1 - k_1^*.$$ (3.7)

Putting these values in (3.6) we get minimum MSE of estimator t_5. The minimum MSE of the estimator t_1, t_2, t_3, t_4 and proposed estimator t_5 is equal to the MSE of combined regression estimator based on two auxiliary variables, which motivated us to study the properties of estimators up to the second order of approximation.

4. Second Order Biases and Mean Squared Errors

Expressing estimator t_i's (i=1,2,3,4,5) in terms of e's (i=0,1), we get

$$t_1 = \overline{Y}(1+e_0)\left\{(1+e_1)^{-\alpha_1}(1+e_1)^{-\alpha_2}\right\} \tag{4.1}$$

Or

$$(t_1 - \overline{Y}) = \overline{Y}\left\{e_0 - \alpha_1 e_1 - \alpha_1 e_0 e_1 - \alpha_2 e_2 - \alpha_2 e_0 e_2 + \alpha_1\alpha_2 e_1 e_2 + \alpha_1\alpha_2 e_0 e_1 e_2 + R_1 e_1^2 + R_1 e_0 e_1^2 \right.$$

$$+ S_1 e_2^2 + S_1 e_0 e_2^2 - R_2 e_1^3 - R_2 e_0 e_1^3 - S_2 e_2^3 - S_2 e_0 e_2^3 - R_2 e_1^3 - \alpha_2 R_1 e_2 e_1^2 - \alpha_1 S_1 e_1 e_2^2$$

$$\left. + \alpha_2 R_2 e_1^3 e_2 + \alpha_1 R_1 e_1 e_2^3 \right\} \tag{4.2}$$

Squaring both sides and neglecting terms of *e*'s having power greater than four, we have

$$\left(t_1 - \overline{Y}\right)^2 = \overline{Y}^2\left[e_0^2 + \alpha_1^2 e_1^2 + \alpha_2^2 e_2^2 - 2\alpha_1 e_0 e_1 - 2\alpha_2 e_0 e_2 + 2\alpha_1\alpha_2 e_1 e_2 - 2\alpha_1 e_0^2 e_1 - 2\alpha_2 e_0^2 e_2 \right.$$

$$+ (2R_1 + 2\alpha_1^2)e_0 e_1^2 + 2S_1 e_0 e_2^2 - 2\alpha_1^2\alpha_2 e_1^2 e_2 - 2S_1\alpha_1 e_1 e_2^2 - 2R_1\alpha_1 e_1^3 + 6\alpha_1\alpha_2 e_0 e_1 e_2$$

$$+ (\alpha_1^2 + 2R_1)e_0^2 e_1^2 + (\alpha_2^2 + 2S_1)e_0^2 e_2^2 + (\alpha_1^2\alpha_2^2 + 2R_1 S_1)e_1^2 e_2^2 - (4\alpha_1^2\alpha_2 + 6R_1\alpha_1)e_0 e_1^2 e_2$$

$$- 4\alpha_1(S_1 + \alpha_2^2)e_0 e_1 e_2^2 + 4\alpha_1\alpha_2 e_0^2 e_1 e_2 - 2(R_2 + 2\alpha_1 R_1)e_0 e_1^3 - 2(S_2 + 2\alpha_2 S_1)e_0 e_2^3$$

$$\left. - 2\alpha_1(S_2 - \alpha_2 S_1)e_1 e_2^2 + 2\alpha_2(R_2 + \alpha_1 R_1)e_1^2 e_2 + (R_1^2 + 2\alpha_1 R_2)e_1^4 + (S_1^2 + 2\alpha_2 S_2)e_2^4\right] \tag{4.3}$$

Taking expectations, and using theorem 1.1 we get the MSE of the estimator t_1 up to the second order of approximation as

$$MSE_2(t_1) = \overline{Y}^2\left[V_{200} + \alpha_1^2 V_{020} + \alpha_2^2 V_{002} - 2\alpha_1 V_{110} - 2\alpha_2 V_{101} + 2\alpha_1\alpha_2 V_{011} - 2\alpha_1 V_{210} - 2\alpha_2 V_{201}\right.$$

$$\left. + (2R_1 + 2\alpha_1^2)V_{120} + 2S_1 V_{102} - 2\alpha_1^2\alpha_2 V_{021} - 2S_1\alpha_1 V_{012} - 2R_1\alpha_1 V_{030} + 6\alpha_1\alpha_2 V_{111}\right.$$

$$+ (\alpha_1^2 + 2R_1)V_{220} + (\alpha_2^2 + 2S_1)V_{202} + (\alpha_1^2\alpha_2^2 + 2R_1S_1)V_{022} - (4\alpha_1^2\alpha_2 + 6M_1\alpha_1)V_{121}$$

$$- 4\alpha_1(S_1 + \alpha_2^2)V_{112} + 4\alpha_1\alpha_2 V_{211} - 2(R_2 + 2\alpha_1 R_1)V_{130} - 2(S_2 + 2\alpha_2 S_1)V_{103}$$

$$- 2\alpha_1(S_2 - \alpha_2 S_1)V_{012} + 2\alpha_2(R_2 + \alpha_1 R_1)V_{021} + (R_1^2 + 2\alpha_1 R_2)V_{040} + (S_1^2 + 2\alpha_2 S_2)V_{004}\big] (4.4)$$

where, $\quad R_1 = \dfrac{\alpha_1(\alpha_1 + 1)}{2}, \quad R_2 = \dfrac{\alpha_1(\alpha_1 + 1)(\alpha_1 + 2)}{6}, \quad R_3 = \dfrac{\alpha_1(\alpha_1 + 1)(\alpha_1 + 2)(\alpha_1 + 3)}{24},$

$$S_1 = \dfrac{\alpha_2(\alpha_2 + 1)}{2}, \quad S_2 = \dfrac{\alpha_2(\alpha_2 + 1)(\alpha_2 + 2)}{6}, \quad S_3 = \dfrac{\alpha_2(\alpha_2 + 1)(\alpha_2 + 2)(\alpha_2 + 3)}{24}.$$

Similarly, MSE expression of estimator t_2 is given by

$$MSE_2(t_2) = \overline{Y}^2\big[V_{200} + \lambda_1^2(V_{020} + V_{220} + 3V_{040} + 2V_{120} - 2V_{030} - 4V_{130})$$

$$+ \lambda_2^2(V_{002} + V_{202} + 3V_{004} + 2V_{102} - 2V_{003} - 4V_{103})$$

$$+ 2\lambda_1(-V_{110} - V_{210} + V_{120} + V_{220} - V_{130}) + 2\lambda_2(-V_{101} - V_{201} + V_{202})$$

$$+ 2\lambda_1\lambda_2(V_{011} + 2V_{111} - V_{012} - 2V_{112} + V_{013} + V_{211} - V_{021} - 2V_{121} + V_{022} + V_{031})\big] \quad (4.5)$$

MSE expression of estimator t_3 is given by

$$MSE_2(t_3) = \overline{Y}^2\big[V_{200} + w_1^2\overline{X}_1\{\alpha^2\theta^2(V_{020} + V_{220} + 2V_{120}) + 2A_1\theta^2(V_{120} + V_{220})\}$$

$$+ w_2^2\overline{X}_2\{\alpha^2\theta^2(V_{002} + V_{202} + 2V_{120}) + 2A_1\theta^2(V_{120} + V_{202})\}$$

$$+ 2w_1 w_2\overline{X}_1\overline{X}_2\{\alpha^2\theta^2(V_{211} + 2V_{111}) + 2A_1\theta^2(V_{111} + V_{211}\}$$

$$+ 2w_1^3 w_2\overline{X}_1^3\overline{X}_2(A_1^2\theta^4 + 4A_2\alpha\theta^4)V_{031} + 2w_1 w_2^3\overline{X}_1\overline{X}_2^3(A_1^2\theta^4 + 4A_2\alpha\theta^4)V_{013}$$

$$- 2\alpha\theta w_1\overline{X}_1(V_{110} + V_{210}) - 2\alpha\theta w_2\overline{X}_2(V_{101} + V_{201})$$

$$+ 3w_1^2 w_2\overline{X}_1^2\overline{X}_2(-2A_2\theta^3 V_{121} - 4A_1\alpha\theta^3 V_{121} - 2A_1\alpha\theta^3 V_{012})$$

$$+ 3w_1\overline{X}_1 w_2^2\overline{X}_2^2(-2A_2\theta^3 V_{112} - 4A_1\alpha\theta^3 V_{112} - 2A_1\alpha\theta^3 V_{012})$$

$$+ w_1^4 \overline{X}_1^4 \left(A_1^4 \theta^4 + 2A_2 \alpha \theta^4 \right) V_{040} + w_2^4 \overline{X}_2^4 \left(A_1^4 \theta^4 + 2A_2 \alpha \theta^4 \right) V_{002}$$

$$+ w_1^3 \overline{X}_1^3 \left(-2A_2 \theta^3 V_{130} - 4A_1 \alpha \theta^3 V_{130} - 2A_1 \alpha \theta^3 V_{030} \right)$$

$$+ w_2^3 \overline{X}_2^3 \left(-2A_2 \theta^3 V_{103} - 4A_1 \alpha \theta^3 V_{103} - 2A_1 \alpha \theta^3 V_{003} \right)$$

$$+ 6 w_1^2 \overline{X}_1^2 w_2^2 \overline{X}_2^2 \left(A_1^2 \theta^4 + 2A_2 \alpha \theta^4 \right) V_{022} \Big] \tag{4.6}$$

MSE expression of estimator t₄ is given by

$$MSE_2(t_4) = \overline{Y}^2 \Big[V_{200} + \frac{\beta_1^2}{4} V_{020} + \frac{\beta_2^2}{4} V_{002} - \beta_1 V_{110} - \beta_1 V_{210} \left\{ M + \frac{\beta_1^2}{4} \right\} + \frac{V_{102}}{2} \left\{ N + \frac{\beta_2^2}{4} \right\}$$

$$- V_{021} \left\{ M + \beta_1^2 \beta_2 \right\} - V_{012} \left\{ N + \beta_2^2 \beta_1 \right\} + \frac{3}{2} \beta_1 \beta_2 V_{111} + \frac{1}{2} \beta_1 \beta_2 V_{011} - \frac{3}{4} \beta_1 M V_{030} - \frac{1}{2} \beta_2 N V_{003}$$

$$+ \frac{V_{220}}{2} \left\{ M + \frac{\beta_1^2}{4} \right\} + \frac{V_{202}}{2} \left\{ N + \frac{\beta_2^2}{4} \right\} + \frac{V_{022}}{8} \left\{ \frac{\beta_1^2 \beta_2^2}{2} + \beta_1 + \beta_2 Q + MN \right\} - \frac{V_{130}}{4} \left\{ O + 2\beta_1 M \right\}$$

$$- \frac{V_{103}}{4} \left\{ P + 2\beta_2 N \right\} + \frac{V_{031}}{8} \left\{ \beta_1 Q + O + SM \right\} + \frac{V_{013}}{8} \left\{ \beta_2 R + \beta_1 P + SN \right\}$$

$$- \frac{V_{121}}{4} \left\{ Q + 2\beta_1^2 \beta_2 + \beta_2 M \right\} - \frac{V_{112}}{4} \left\{ 2\beta_2^2 \beta_1 + 2\beta_1 N + R \right\} + - \frac{V_{040}}{16} \left\{ 2\beta_1 O + M^2 \right\}$$

$$+ \frac{V_{004}}{16} \left\{ 2\beta_2 P + N^2 \right\} + \frac{V_{211}}{2} \left\{ \beta_1^2 \beta_2 + S \right\} \Big] \tag{4.7}$$

where,

$$M = \left(\beta_1 + \frac{\beta_1^2}{2} \right), \quad N = \left(\beta_2 + \frac{\beta_2^2}{2} \right), \quad O = \left(\beta_1^2 + \frac{\beta_1^3}{6} \right)$$

$$P = \left(\beta_2^2 + \frac{\beta_2^3}{6} \right), \quad Q = \left(\beta_1 \beta_2 + \frac{\beta_1^2 \beta_2}{2} \right), \quad R = \left(\beta_1 \beta_2 + \frac{\beta_1 \beta_2^2}{2} \right)$$

MSE of Proposed estimator t₅ up to second order of approximation

Expanding right hand side of equation (3.2) and neglecting terms of e's having power greater than four, we get

$$t_5 - \overline{Y} = \overline{Y}\left[e_0 + k_1\left(-\delta_1\eta_1 e_1 + M_1 e_1^2 - M_2 e_1^3 + M_3 e_1^4\right) + k_2\left(-\delta_2 e_2 + N_1 e_2^2 - N_2 e_2^3 + N_3 e_2^4\right)\right.$$

$$\left. + k_1\left(-\delta_1\eta_1 e_0 e_1 + M_1 e_0 e_1^2 - M_2 e_0 e_1^3\right) + k_2\left(-\delta_2 e_0 e_2 + N_1 e_0 e_2^2 - N_2 e_0 e_2^3\right)\right] \qquad (4.8)$$

Squaring both sides of (4.8) and neglecting terms of e's having power greater than four, we have

$$\left(t_5 - \overline{Y}\right)^2 = \overline{Y}^2\left[e_0^2 + k_1^2\left\{\delta_1^2\eta_1^2(e_1^2 + e_1^2 e_2^2 + 2e_0 e_1^2) + 2\delta_1\eta_1(M_1 e_1^4 - 2M_1 e_1^3) + M_1^2 e_1^4\right\}\right.$$

$$+ k_2^2\left\{\delta_2^2(e_2^2 + e_0^2 e_2^2 + 2e_0 e_2^2) + 2\delta_2(N_1 e_0 e_2^3 + N_1 e_1^2 + N_2 e_2^4) + N_1^2 e_2^4\right\}$$

$$+ 2k_1\left\{\delta_1\eta_1(-e_0 e_1 - e_0^2 e_1) + M_1(e_0 e_1^2 + e_0^2 e_1^2) - M_2 e_0 e_1^3\right\}$$

$$+ 2k_2\left\{\delta_2(-e_0 e_2 - e_0^2 e_2) + N_1(-e_0 e_2^2 - e_0^2 e_2^2) - N_2 e_0 e_2^3\right\}$$

$$\left. + 2k_1 k_2\left\{\delta_1\delta_2\eta_1(e_1 e_2 + 2e_0 e_1 e_2 + e_0^2 e_1 e_2) + \delta_1\eta_1(N_1 e_1 e_2^2 + N_2 e_1 e_2^3)\right\}\right] \qquad (4.9)$$

Taking expectations on both sides of (4.9) and using theorem1.1, we get the MSE of estimator t_5, up to the second order of approximation as

$$\text{MSE}_2(t_5) = \overline{Y}^2\left[V_{200} + k_1^2\left\{\delta_1^2\eta_1^2(V_{020} + V_{022} + 2V_{120}) + 2\delta_1\eta_1(M_1 V_{040} - 2M_1 V_{030}) + M_1^2 V_{040}\right\}\right.$$

$$+ k_2^2\left\{\delta_2^2(V_{002} + V_{202} + 2V_{102}) + 2\delta_2(N_1 V_{103} + N_1 V_{030} + N_2 V_{004}) + N_1^2 V_{004}\right\}$$

$$+ 2k_1\left\{\delta_1\eta_1(-V_{110} - V_{210}) + M_1(V_{120} + V_{220}) - M_2 V_{130}\right\}$$

$$+ 2k_2\left\{\delta_2(-V_{101} - V_{201}) + N_1(-V_{102} - V_{202}) - N_2 V_{103}\right\}$$

$$\left. + 2k_1 k_2\left\{\delta_1\delta_2\eta_1(V_{011} + 2V_{111} + V_{211}) + \delta_1\eta_1(N_1 V_{012} + N_2 V_{013})\right\}\right] \qquad (4.10)$$

5.   Numerical Illustration

For a natural population data, we have calculated the mean square error's of the estimator's and compared MSE's of the estimator's under first and second order of approximations.

Data Set

The data for the empirical analysis are taken from Book, "An Introduction to Multivariate Statistical Analysis", page no. 58, 2nd Edition By T.W. Anderson.

The population consist of 25 persons with Y= Head length of second son, X= Head length of first son and Z= Head breadth of first son. The following values are obtained from Raw data given on page no. 58.

$\overline{Y} = 183.84,\ \overline{X} = 185.72,\ \overline{Z} = 151.12, N = 25, n = 7$ and

V020=0.000244833,V200=0.000306792,V020=0.000284171,V110=0.00020986,V011=0.000193753, V101= 0.000189972, V111= -0.000059732, V210 = -0.0000004582, V201= -0.0000002.77, V021= -0.0000002775, V102= -0.0000002354, V120= -0.00000036455, V012=0.00000025179, V202=0.000013,V003=0.000001544,V031=0.3893411 ,V013=0.380025, V030= -0.00001363,V103=0.00001215,V040=0.0000214,V220=0.000015 V022=0.001624,V121=0.0000115,V211=0.0000122,V004=0.00001384,V112=0.000000085

Table 5.1: MSE's of the estimators t_i (i=1,2,3,4,5)

Estimators	MSE	
	First order	**Second order**
t_1	4.508	16156.644
t_2	4.508	27204.321
t_3	4.508	17679.890
t_4	4.508	20928.689
t_5	4.508	275.926*

*for $\delta_1 = \delta_2 = 1$

This table shows the comparison of estimators on the basis of MSE because $\bar{y}$ cannot be extended up to second order of approximation therefore, we are unable to calculate PRE for second order approximation.

6. Conclusion

In the Table 5.1 the MSE's of the estimators t_1, t_2 , t_3, t_4 and t_5 are written under first order and second order of approximations. It has been observed that for all the estimators, the mean squared error increases for second order. Observing second order MSE's we conclude that the estimator t_5 is best estimator among the estimators considered here for the given data set.

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