Using MATLAB for Linear Algebra

This is a collection of basic information and techniques for using MATLAB to explore matrix properties, manipulations, and identities. These only address "numerical" (x is a particular number or vector of numbers or matrix of numbers) rather than "symbolic" (x is a variable without any particular value) functions of MATLAB.

1. Overview: General Things to Know

- a. π is pi and $\sqrt{-1}$ is either i or j.
- b. MATLAB versions of common functions (these are applied *element-by-element* if the argument is a vector or matrix):

Function	MATLAB	Example
x^n	x^n	$x^2 \longrightarrow x.^2$
e^x	exp(x)	$e^{-5} \longrightarrow \exp(-5)$
$\ln x$	log(x)	$\ln\pi\longrightarrow { t log(pi)}$
$\sinh x, \cosh x$	sinh(x), cosh(x)	$\sinh 1 \longrightarrow \mathtt{sinh}(1)$
$\sin x, \cos x$	sin(x), cos(x)	$\cos\pi\longrightarrow\cos(exttt{pi})$
$\sin^{-1} x$ or $\arcsin x$	asin(x)	$rcsin 0.5 \longrightarrow exttt{asin}(0.5)$
\sqrt{x}	sqrt(x)	$\sqrt{2.5} \longrightarrow exttt{sqrt(2.5)}$

There are matrix versions of exp, log, sqrt called expm, logm, sqrtm, see below.

- c. You can use the ↑ and ↓ keys to move back and forth through the list of past commands ("history"). If you bring back a previous command, you can change it (use the ← and → keys to move to parts you want to delete or replace or add something) and rerun the commands (by pressing "Enter").
- d. Getting help: To find help for any function (e.g., exp), type help exp (or whatever the function is) at the >> command prompt. Or, bring up the "Help Browser" using F1 (or "MATLAB Help" under the "Help" menu in the main MATLAB window).
- e. Use the clear statement to set all variables to zero (to avoid conflicts with previous definitions).

2. Complex Numbers

a. Cartesian form. You can use either i or j for $\sqrt{-1}$ (since we're in a physics class, we'll use i exclusively). If i appears in a numerical expression, MATLAB will simply interpret the number as a complex number. For example, if we want to set z equal to 3+4i, simply type it in this way:

$$>> z = 3 + 4*i$$

We could even omit the * in this case, but it is best to leave it in, since we need it if we are using a variable such as y:

```
>> x = 1/sqrt(2);
>> y = -1/sqrt(3);
>> z = x + i*y
```

We can use any of the standard functions (e.g., exponentials or trigonometric functions) directly. For example,

```
\Rightarrow sin(1-sqrt(2)*i)
ans = 1.8329 - 1.0455i
```

Note that the answer comes back in standard x + yi form with decimals (as opposed to fractions or explicit π 's).

b. Polar form. If we want to enter a number in the form $re^{i\theta}$, we just use the exp function:

```
>> r = 1;
>> theta = pi/6;
>> z = r*exp(i*theta)
z = 0.8660 + 0.5000i
```

Note that the answer comes back in Cartesian form.

- c. **Arithmetic with complex numbers.** All of the standard operations (+ * /) will work as expected (i.e., correctly) with complex numbers.
- d. Complex conjugate. The function conj takes the complex conjugate:

```
>> conj(2-3*i)
ans = 2.0000 + 3.0000i
```

e. Real and imaginary parts. The functions real and imag do the trick:

```
>> z = (1 + i)/(2 - i);
>> real(z)
ans = 0.2000
>> imag(z)
ans = 0.6000
```

Note that you always end up with the decimal version of numbers.

f. Modulus and angle. You can find r and θ using the abs and angle functions:

```
>> z = 2 * exp(i*pi/4)
z = 1.4142 + 1.4142i
>> abs(z)
ans = 2
>> angle(z)  % answer should be pi/5 = 0.7854
ans = 0.7854
```

3. Creating Vectors and Matrices and Accessing Elements

Both vectors and matrices are specified by entries between []'s with semicolons ; used to separate rows. So

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 2 & -5 & 4 \\ -1 & 3 & -2 \end{bmatrix} \qquad B = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \qquad C = \begin{pmatrix} 3 & 4 & 5 \end{pmatrix}$$

are entered as

To get the "ij" matrix element of A, use A(i,j). So

>>
$$A(1,2)$$

ans = -2
>> $A(2,2)$
ans = -5

The n^{th} row is A(n,:) and the m^{th} column is A(:,m). So the 2nd row and 3rd columns are:

4. Special Matrices

- a. For a 3×3 unit matrix, use eye(3) while for $N \times N$ use eye(N).
- b. zeros(N) is an $N \times N$ matrix of zeros while zeros(1,N) is an N-dimensional row vector of zeros and zeros(N,1) is an N-dimensional column vector of zeros.
- c. ones(N) is an $N \times N$ matrix of ones while ones(1,N) is an N-dimensional row vector of ones and ones(N,1) is an N-dimensional column vector of ones.
- d. Random matrices. Use rand(N) to generate an $N \times N$ matrix whose entries are random numbers uniformly distributed between 0 and 1. E.g.,

```
>> M = rand(3)
M =

0.1239   0.4238   0.0785

0.7745   0.1592   0.7084

0.1123   0.2949   0.0181
```

The numbers are really "pseudo-random" numbers. See help rand for more info. To generate a uniform distribution of random numbers on a specified interval [a,b], multiply the output of rand by (b-a), then add a. For example, to generate a 5-by-5 array of uniformly distributed random numbers on the interval [10,50],

```
>> a = 10; b = 50;
>> x = a + (b-a) * rand(5);
```

e. Random complex matrix. We can combine a real and an imaginary random matrix to get a complex one:

```
>> C = rand(3) + i * rand(3)

C =

0.8189 + 0.3162i  0.2035 + 0.3700i  0.3652 + 0.0847i

0.4283 + 0.5119i  0.5217 + 0.2280i  0.9393 + 0.6571i

0.3677 + 0.3355i  0.6054 + 0.9477i  0.4161 + 0.5234i
```

f. Normally distributed random matrices. Use randn(N) to generate an $N \times N$ matrix whose entries are random numbers distributed according to a normal distribution (i.e., a bell-shaped curve) with mean zero and standard deviation one. E.g.,

```
>> M = randn(3)

M =

-0.0956 -1.3362 -0.6918

-0.8323 0.7143 0.8580

0.2944 1.6236 1.2540
```

5. Matrix Operations

- a. **Matrix multiplication.** Ordinary matrix multiplication is performed by using *. In contrast, .* is used for element-by-element operations (e.g., A*B is matrix multiplication while A.*B multiplies each element in A by the corresponding one in B).
- b. Inverse of a matrix. The inverse of the square matrix A is designated A^{-1} and is defined by $AA^{-1} = A^{-1}A = I$, where I is the identity matrix. We can find the inverse of a matrix either by raising A to the -1 power, i.e., A^{-1} , or with the inv(A) function.
- c. **Determinant of a matrix.** The det function returns the determinant of a square matrix. That is, det(A) gives the determinant of the matrix A.
- d. **Exponential of a matrix.** The expm function returns the exponential of a matrix, as defined by its Taylor series. So expm(A) gives e^A . [Note: if you use exp(A) by mistake (no m at the end of the name), you'll get a matrix whose elements are each the exponential of the corresponding matrix element in A.]
- e. **General matrix functions.** To calculate the cosine, sine, or logarithm or a matrix A, use funm(A,'cos'), funm(A,'sin'), or funm(A,'log').
- f. Trace of a matrix. The sum of the diagonal matrix element of matrix A is trace(A).
- g. Adjoint and transpose of a matrix. The adjoint of matrix A (designated A^{\dagger}), which is the complex conjugate of the transpose, is found from A or the function ctranspose(A). If you want just the transpose A^T of A and not the complex conjugate, use A. or transpose(A).
- h. Eigenvalues and eigenvectors of a matrix. E = eig(A) gives a vector with the eigenvalues of the matrix A. [V,D] = eig(A) gives a diagonal matrix D of eigenvalues and a matrix V whose *columns* are the corresponding eigenvectors.

The n^{th} row of M is M(n,:) and the m^{th} column is M(:,m). So the eigenvector v_1 and eigenvalue λ_1 are (using random normally distributed matrix M from above.)

```
0.6074
-0.5495
>> lambda1 = D(1,1)
lambda1 = -0.8479
We can verify that Mv_1 = \lambda_1 v_1:
>> M*v1
ans =
-0.4863
-0.5150
0.4660
>> lambda1*v1
ans =
-0.4863
-0.5150
0.4660
```

- i. Powers of Matrices. To get A^3 , just use A^3 , and so on.
- j. **Bra's and ket's.** We associate the "ket" $|V\rangle$ (or $|1\rangle$ or whatever) with a column vector. The "bra" $\langle V|$ is the adjoint of $|V\rangle$, i.e., $\langle V|=(|V\rangle)^{\dagger}$. Then $\langle V|W\rangle$ is simply the inner product, which is a generalized dot product. Note that $\langle W|V\rangle=\langle V|W\rangle^*$. Examples:

```
>> Vket = [2; 3i]
Vket =
   2.0000
        0 + 3.0000i
>> Vbra = Vket'
                   % note that the i's change sign
Vbra =
                           0 - 3.0000i
   2.0000
>> Wket = [i; -1]
Wket =
        0 + 1.0000i
  -1.0000
>> Vbra*Wket
                   % just row vector times column vector
ans = 0 + 5.0000i
>> Wket'*Vket
                   % in this order, we get the complex conjugate
ans = 0 - 5.0000i
```

k. Unit Vectors. Given $|V\rangle$, its magnitude is $\sqrt{\langle V|V\rangle}$, so the unit vector is $|V\rangle/\sqrt{\langle V|V\rangle}$. In MATLAB, we can use the norm function for the magnitude. E.g.,

```
>> Vket_unit = Vket/sqrt(Vbra*Vket) % the basic definition Vket_unit =
```

l. Isolating the Diagonal Elements. If M is a square matrix, then diag(M) is a vector with the matrix elements on the main diagonal. E.g., for the normally distributed random matrix M:

```
>> diag(M)
ans =
-0.0956
0.7143
1.2540
```

To cube each diagonal element, use diag(M). 3 (note the "." before the "). To get a square matrix of the same size as M but with just it's diagonal elements and zeros elsewere, use diag(diag(M)).

- m. Random Hermitian matrices. Generate a random complex matrix A and then a random hermitian matrix by $H = (A + A^{\dagger})/2$.
- n. Random Unitary matrices. Generate a random Hermitian matrix H as above and then $U=e^{iH}$ is unitary (so $UU^{\dagger}=I$). Use the MATLAB matrix exponentiation function expm.

6. Timing Matrix Operations

The functions tic and toc can be used to time one or more MATLAB operations (not just matrix functions). A stopwatch is started with tic and stopped with toc, which then displays the elapsed time. For example, to time how long it takes to calculate the determinant of a 100×100 matrix:

```
>> M = rand(100);
>> tic; det(M); toc
Elapsed time is 0.130749 seconds.
```

7. Condition Number

To find the condition number of a matrix, use cond(M). A number near one is good; if the number is large the matrix is ill-conditioned. See the help for svd and gsvd to learn about (generalized) singular value decomposition.

8. Solving Matrix Equations

Suppose we want to solve the simultaneous equations

$$3x - 2y = 17$$
$$5x + 3y = 3$$

We write this in the form MX = B, with M a matrix and B a column vector, then find the desired column vector X from $X = M^{-1}B$ using the MATLAB inv function:

```
>> M = [3 -2; 5 3] % separate the rows of the matrix with ;'s
M =
     3
          -2
     5
           3
>> B = [17; 3]
                    % note the ; to make it a column vector (two rows)
B =
    17
     3
>> X = inv(M)*B
                    % regular matrix multiplication uses * (not .*)
X =
    3.0000
   -4.0000
```

That's the answer: x = 3 and y = -4. Note: If you had defined the vector B as a row vector instead of a column vector, you would have received an error like this:

An alternative way to using inv to solve the equation is:

```
>> X = M\B % The "\" means "matrix left division"
```

which is actually preferred because it solves the problem much more efficiently.

9. Scripts and Functions in MATLAB

Here is a very brief introduction to scripts and functions using the my_area.m script and the circle_area.m function as examples. They are run by typing the name (without the .m ending) at the command prompt, e.g., >> my_area will run my_area.m.

- a. % is used to mark a comment to help explain what the program is doing (or supposed to do!). Everything on a line after a % is ignored. Examples:
 - % This is a comment line only; no MATLAB instructions.

```
height = 5 % This comment might say that height is in meters
```

- b. A semicolon; is used at the end of a line to suppress extra output from MATLAB, which might be distracting.
- c. input is used to get a value from the user for a variable. The general form is:

```
variable_name = input('message to be displayed')
For example,
```

```
radius = input('Enter the radius of a circle: ');
```

d. disp is used for output of a message (in the form of text enclosed in single quotes) or the value of a variable. For example,

```
disp('The area is: ')
disp(area)
```

e. A MATLAB function is like a script but it starts with a function declaration with a list of outputs between []'s, then an =, then the name of the function (same as the filename), then the list of inputs in ()'s. Example:

```
function [area] = circle_area (radius)
which takes radius as input and returns area.
```

10. Numerical Two-Dimensional Plotting

Here we outline how to make two-dimensional graphs using plot, line, and loglog, which take arrays of numerical values as input.

a. To plot $\sin x$ from $-\pi$ to $+\pi$, we first define a set of points to plot, in the form of a vector (which is considered a $1 \times N$ matrix by MATLAB). We can specify a set of evenly spaced points with spacing 0.1 by:

```
x = -pi:0.1:pi
```

To avoid seeing this vector printed out, add a semicolon to the end:

```
x = -pi:0.1:pi;
```

If instead we want a specified number of points (say 100), then

```
x = linspace(-pi,pi,100);
```

will do ("linspace" is short for "linear space").

b. Then we give the x vector and the function to plot as the y vector to the plot command: plot(x,sin(x))

which should pop up a figure window or make a new plot in an existing window (which may be hidden by other windows). This function makes a regular linear-linear plot.

c. To add a second curve to the same graph (e.g., of $\cos x$ in the same range), use:

```
line(x, cos(x))
```

d. To make a log-log plot instead, we will typically want to space the points logarithmically rather than linearly. To set x equal to 150 points from 10^{-5} to 10^2 , we can use

```
x = logspace(-5,2,150);
To plot x^2e^{-x} from 10^{-10} to 10^1 with 200 points:
x = logspace(-10,1,200);
loglog(x,x.^2.*exp(-x))
```

Note that we use . $\hat{}$ and .* rather than $\hat{}$ rather than *. The "." means to exponentiate or multiply (or divide, etc.) each term in the vector x, rather than trying to operate on entire vectors or matrices. If you forget the "." you'll get an error message.

11. Plotting Complex Functions

We can use plotting commands with functions of a complex variable z if we take the modulus of the function using the abs command. For example, suppose we want to plot the function $f(z) = 1/(z^4 + 1)$ in the complex plane for the real and imaginary parts of z varying from -2 to +2. Here's an excerpt from an M-file to do this.

```
% Set a grid X Y with the desired range (and 20 points on each axis)
[X Y] = meshgrid( linspace(-2,2,20), linspace(-2,2,20));
% Define z = x + i*y for each point in the grid
Z = X + i*Y;
% Evaluate the function we want to study.
\% Note the use of "." before operations like "^" and "/".
f = abs(1./(Z.^4 + 1)); % use "abs" to take the modulus
figure(1);
                            % figure 1 will be a surface plot
surf(X,Y,f); colorbar;
                            % make the plot and add a color bar
xlabel('x-axis'); ylabel('y-axis'); % add labels x and y axes
figure(2);
                                         % figure 2 will be a contour plot
num_contours = 10;
                                         % use num_contours contour lines
contourf(X,Y,f,num_contours); colorbar; % make the plot and add a color bar
xlabel('x-axis'); ylabel('y-axis');
                                        % add labels
```