Radar and Electronic Warfare

1. Preliminaries, Radar Basics, Radar Detection

- 1.1 Preliminaries, brief review of some required math and electromagnetics
- 1.2 Basic pulsed radar, notions of PRF and unambiguous range
- 1.3 Range resolution and detectability
- 1.4 Maximum range, radar range equation
- 1.5 Receiver noise considerations, range ambiguities and solutions
- 1.6 Detection, Hypothesis testing, brief overview of Bayesian theory
- 1.7 Probability of detection and Probability of false alarm
- 1.8 Neyman Pearson criteria, Receiver operating curve (ROC)
- 1.9 Pre and Post Integration, Swerling models.

2. Doppler radar processing and pulse compression

- 2.1 Doppler effect, coherence, I and Q channels
- 2.2 CW radars, FM ranging
- 2.3 Pulse doppler radars and synchronous detectors
- 2.4 Doppler spectra, doppler processing with the FFT, digital filtering
- 2.5 Matched filter and correlation receivers, ambiguity diagram
- 2.6 Pulse compression, chirp, stretch processing, binary phase modulation
- 2.7 Barker, Costas and Frank coding schemes.
- 2.8 Appendix: complex time signals and the analytic signal.

3. Clutter and Tracking

- 3.1 Clutter RCS, airborne and ground clutter
- 3.2 Isodops, altitude return, mainlobe and sidelobe clutter
- 3.3 Doppler ambiguities
- 3.4 Low Medium and High PRF scenarios
- 3.5 MTI and clutter cancellers
- 3.6 Tracking, CORSO, sequential lobing scanning, monopulse techniques
- 3.7 Multiple target tracking: $\alpha\beta$ tracker and introduction to Kalman filtering

4. Electronic Warfare

- 4.1 Introduction and EW radar scenarios, EW hierarchy
- 4.2 Electronic Support (ELINT), receivers
- 4.3 Electronic Attack (Electronic counter measures -ECM),
- 4.4 Types of Radars: surveillance and tracking
- 4.5 Jamming, burn through, J/S ratios, passive EA, etc.
- 4.6 Electronic Protection (Electronic counter-counter measures -ECCM)

5. Wrap up: Conclusions and References