SC11024

2400 Bit Per Second Modem Analog Peripheral

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- 1. Conforms to CCITT V.22 bis V.22, V.21 and Bell 212A and 103 standards.
- 2. Single 5 V supply with 10 mW power down mode
- 3. Analog, digital and remote digital loop back
- 4. Integrated DTMF / Guard Tone Generator, call progress monitor
- 5. Contain an on-chip hybrid
- 6. Programmable audio output
- 7. CMOS technology

GENERAL DESCRIPTION

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The SC11024 is a complete 2400 bps 5 V only modem IC containing all modem functions except the adaptive equalizer. It is used in conjunction with an external controller, such as the IST SC11019 (for parallel bus applications), the SC11020 (for RS-232 applications), the SC11022 (for both configurations), the SC11021, SC11061 or SC11091 ROM less controllers for customized firmware, to

implement a 2400 bps full duplex modem, conforming to CCITT V.22 bis standards. The controller performs all modem control and handshaking functions as well as the adaptive equalization.

The SC11024 operates in 2400 bps QPSK / QAM and 2400 bps PSK as well as 0 to 300 baud FSK modes, compatible with Bell 103 and 212A as well as CCITT V.21, V.22 and V.22 bis standards. When used with the SC11019, SC11020 or SC11022 controllers, the SC11024 becomes an intelligent modem controlled by the industry standard "AT" command set. The interface between the SC11024 modem and the controller is a standard micro controller interface that easily connects to the SC22201 (128 by 8) EE memory for permanent storage of configuration settings and phone numbers.

BLOCK DIAGRAM

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FUNCTIONAL DESCRIPTION OF THE SC11024 MODEM

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The SC11024 includes

- 1. Full Transmitter consisting of
 - Async to Sync converter
 - Scrambler
 - Data Encoder
 - 75% square root of raised consine pulse shaper
 - Quadrature modulator
 - o FSK (Bell 103 and CCITT V.21) modulator
 - o Hybrid
- 2. High band and low band filters
- 3. High band and low band compromise equalizers
- 4. V.22 notch filter (selectable at 550 or 1800 Hz)
- 5. Transmit smoothing filter
- 6. Programmable attenuator for transmit level adjust
- 7. DTMF, 550 Hz, 1300 Hz, 1800 Hz and 2100 Hz tone generator
- 8. Transmit clock circuit for synchronous operation (slave, external and internal modes)
- 9. Pattern generator for generating fixed digital patterns in handshaking mode
- 10. Receive Section consisting of
 - o 64 step programmable gain controller (PGC)
 - o Energy detector at the output of the PGC
 - Hilbert transformer
 - o Quadrature Demodulator (free running carrier) with low pass filters
 - Baud timing recovery circuit (sampling clock of 600 Hz)

- Sync to Async converter
- 11. 8-bit analog to digital converter (ADC)
- 12. Control and Status registers
- 13. 8-bit microprocessor interface with interrupt and multiplexed address / data lines
- 14. Audio output with level adjust

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Since data terminals and computers may not have the timing accuracy required for 2400 / 1200 bps transmission (0.01%), timing correction on the incoming data stream must be made. The Async / Sync converter accepts asynchronous serial data clocked at a rate between 2400 / 1200 Hz $\pm 2.3\%$, -2.5%. It outputs serial data at a fixed rate of 2400 / 1200 Hz $\pm 0.01\%$ derived from the master clock oscillator. To compensate for the input and output rate differences, a stop bit is either deleted or inserted when necessary. If the input data rate is slower than the output data rate, a stop bit is inserted. If the input data rate is faster that the output data rate, a stop bit is deleted. The output of the async / sync converter is applied to the scrambler.

The scrambler is 17-bit shift register clocked at 2400 / 1200 Hz. Outputs from the 14th and 17th stages are exclusive OR'd and further exclusive OR'd with the input data. The resultant data is applied to the D input of the shift register. Outputs from the first four / two stages of the shift register from the quad / dibit that is applied to the QAM / QPSK modulator. The purpose of the scrambler is to randomize data so that the energy of the modulated carrier is spread over the band of interest-either the high band, centered at 2400 Hz, or the low band, centered at 2400 Hz. In the 2400 bps mode, the modem actually sends four bits at a time, called a quad bit. The actual rate of transmission for a quad bit is 600 baud. This is the optimum rate of transmission over the general switched telephone network for a full duplex FDM (frequency division multiplexing) modem because band limit filters in the central office cut off at about 3000 Hz.

In the 2400 bps data rate, the data to be transmitted is divided into groups of four consecutive bits (quad bits). The first two bits of the quad bit are encoded as a phase quadrant change relative to the quadrant occupied by the preceding signal element. The last two bits define one of the four signaling elements associated with the new quadrant.

In the 1200 bps data rate, the data stream is divided into groups of two consecutive bits

(dibits). The dibits are used to determine the phase quadrant change relative to the quadrant occupied by the preceding signal element. The resulting signaling elements from the inphase (I) and quadrature (Q) channels are passed through base band filters with a square root of raised cosine shape. The filtered signals subsequently modulate sine and cosine carriers, and add to form the QAM / QPSK signal. The wave shaped signal is then passed through either the low-band or high-band filter, depending upon originate or answer mode selection.

For low speed operation, the FSK modulator is used. It produces one of four precision frequencies, depending upon originate or answer mode selection and the 1 (mark) or 0 (space) level of the transmit data. Different frequencies are used for V.21 and 212A modes. The frequencies are produced from the master clock oscillator using programmable dividers. The dividers respond quickly to data changes, introducing negligible bit jitter while maintaining phase coherence. The output of the FSK modulator is applied to appropriate filter when the low speed mode of the operation is selected.

The filter section consists of low-band (1200 Hz) and high-band (2400 Hz) filters, half channel compromise amplitude and group delay equalizers for both bands, smoothing filters for both bands, and multiplexers for the transmit and receive signals through the appropriate band filters. For CCITT V.22 bis applications, a notch filter is included that can be programmed for either 550 Hz or 1800 Hz. In call progress monitor mode, the low band filter is scaled down by a factor of 2.5 to center it over a frequency range of 300 to 600 Hz. thus, during call establishment in the originate mode, call progress tones can be monitored through the scaled low band filter and the modem answer tone or voice can be monitored through the unscaled high band filter.

The low band filter is a 10th order switched capacitor band pass filter with a center frequency of 1200 Hz. In the originate mode, this filter is used in the transmit direction; in the answer mode, it is used in the receive direction. When analog loop back is used in the originate mode, this filter, together with the low band delay equalizer, is in the test loop.

The low band delay equalizer is a 10th order switched capacitor all pass filter that compensates for the compromise line characteristics, producing a flat delay response within the pass band.

The high band pass is a 10th order switched capacitor band pass filter with a center frequency of 2400 Hz. In the answer mode this filter is used in transmit direction; in originate mode, it is used in the receive direction. When analog loop back is used in the answer mode, this filter, together with the high band delay equalizer, will be in the test loop.

The high band delay equalizer is a 10th order switched capacitor all pass filter that compensates for the group delay variation of the high band filter and half of the compromise line characteristics, producing flat delay response within the pass band. The transmit smoothing filter is a second-order low pass switched capacitor filter that adds the modem transmit signal to the V.22 guard tones. It also provides a 2 dB per stop programmable gain function to set the output level.

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The receive section consists of an energy detector, programmable gain control (PGC), part of the QAM / QPSK demodulator, FSK demodulator, 8-bit ADC and sync / async converter.

The received signal is routed through the appropriate band pass filter and applied to the energy detector and PGC circuit. The energy detector provides direction within 17 to 24 msec. It is set to turn on when the signal exceeds -43 dBm and turn off when the signal falls below -48 dBm measured at the chip. A 2 dB minimum hysteresis is provided between the turn on and turn off levels. In call progress mode, the energy detector is connected to the output of the PGC to allow detection level adjustment.

The output of the receive filter is applied to the programmable gain control (PGC). This circuit has a wide overall range of 47.25 dB and provides 64 steps of 0.75 dB / step. The PGC gain is controlled by the external processor. It also provides auto-zeroing to minimize the output DC offset voltage.

The QAM /QPSK demodulator uses a coherent demodulation technique. Output of the programmable gain control (PGC) is applied to a Hilbert transformer that produces an in phase and 90° out of phase component. These components are then demodulated to base band in a mixer stage where individual components are multiplied by a free-running carrier. The base band components are low pass filtered to produce I and Q (Inphase and Quadrature) channel outputs. The I and Q channel outputs are both filtered by 300 Hz band pass filters. Then they are rectified, summed and passed through a band pass filter giving 600 Hz signal. This signal is applied to a digital phase lock loop (DPLL) to produce a baud rate clock. Using the recovered clock signal, the I and Q channels are sampled and digitized into 8-bit samples by the ADC. Each channel (I and Q) is sampled twice during a baud period, once at the middle and once at the end of the baud period, allowing T/2 or T sampling operation. The external processor is interrupted once every baud period (1.667 msec). The processor should read the I and Q samples (within 100 µs from the time interrupt is issued), and perform adaptive equalization, carrier phase tracking, data decoding, and data descrambling. One quad / dibit is transferred from the SC11024 during each baud period.

In the asynchronous mode, data received from the processor is applied to the sync / async converter to reconstruct the originally transmitted asynchronous data. For data which had stop bits selected at the transmitter (over speed data), these stop bits are re-inserted. Under speed data is passed essentially unchanged. The sync / async converter has two modes of operation. In the basic signaling mode, the buffer can accept an over speed which corresponds to one missing stop bit in eight characters. The length of the start bit and data elements will be the same, and the stop bit will be reduced by 12.5%. In the extended signaling range, the buffer can accept one missing stop bit in four characters and the stop bits will be reduced by 25% to allow for over speed in the transmitting terminal. Output of the sync / async converter, along with the output of the FSK demodulator, is applied to a multiplexer. The multiplexer selects the appropriate output, depending on the operating speed and output data received on the RXD pin.

For low speed operation, the FSK demodulator is used. The output of The PGC amplifier is passed through a zero crossing detector and applied to a counter that is reset on zero crossings detector and applied to a counter that is reset on zero crossings. The counter is designed to cycle at a rate 4 times faster than the carrier signal. the counter output is low pass filtered and hard limited to generate FSK data.

To improve the performance of the receiver at low signal, while maintaining a wide amplitude range, a 1-bit AGC circuit is placed prior to the band pass filter. The decision thresholds of this AGC are controlled by the AGCVT bit. When AGCVT = 1, the thresholds will be 6 dB further apart than when AGCVT = 0, so that the probability of gain change will be reduced. The status of the AGC gain is available through the AGCO bit. AGC will have 8 dB more gain when AGCO = 1. Status of AGCO should be monitored at every baud timing period and when it makes a transition (causing a gain -hit) the PGC's gain should be modified accordingly to prevent divergence of the adaptive equalizer.

Hybrid Back Top

The signal on the phone line is the sum of the transmit and receive signals. The hybrid subtracts the transmitted signal from the signal on the line to form the received signal. It is important to match the hybrid impedance as closely as possible to the telephone line to produce only the received signal. When the internal hybrid is used, by turning the "hybrid" code on through the interface, this matching is provided by an external resistor connected between the TXA and RXA pins on the SC11024. The filter section provides sufficient attenuation of the out-of-band signals to eliminate leftover transmit signals from the received signal. The hybrid also acts as a first order low pass antialiasing filter. The hybrid can be deactivated by the controller.

The SC11024 internal hybrid is intended to simplify the phone line interface. The internal hybrid can compensate for the loss in the line coupling transformer used in the DAA. By tying the GS pin to AGND, V_{REF} or V_{CC} , compensation levels of 0, +2, +3 dB, respectively are provided.

With a higher loss transformer, some degradation in performance at lower signal levels will occur. Specifically, the bit error rate, when operating at receive signal levels below -40 dBm in the presence of noise, will be higher. The energy on / off levels measured at the line will also be different from those specified at the chip. An external hybrid circuit, shown in figure 2, can be used to overcome these losses and achieve maximum performance. In this case, the internal hybrid must be turned off by setting bit 6 of the TXCR register to 0.

The external hybrid circuit uses two operational amplifiers, one in the transmit path and the other in the receive path. The SC11024 internal transmit stage provides a gain of 6 dB over the transmit signal level desired at the line. Under ideal conditions, with no loss in the transformer and perfect line matching, the signal level at the line will then be the desired value. In practice, however, there is impedance mismatch and a loss in the coupling transformer. Therefore, it may be desired to provide a gain in the transmit and receive paths to overcome the loss. To receive gain (GR) and transmit gain (GT) are set by the ratios of resistors R2, R1 and R6, R5, respectively (Figure 2).

The circuit can be analyzed as follows:

$$V_R = -R2 / R1 (V_{TR}) + (1 + R2 / R1) (R4 / R3 + R4) V_v$$

Complete datasheet of 11024CN/CV/CQ

$$V_y = -R6 / R5 V_X$$

If R6 / R5 is chosen to equal the loss in the transformer, it can be assumed that V_y is twice as higher as V_{TX} (transmit portion of the total line signal).

Since
$$V_{TR} = V_{TX} + V_{RX}$$
 and $V_y = 2V_{TX}$,

$$V_R = -R2/R1 (V_{TX} + V_{RX}) + (1 + R2/R1) (R4/R3 + R4) 2V_{TX}$$

= -R2/R1 V_{RX} + [(1 + R2/R1) (2R4/R3 + R4) -R2/R1] V_{TX}

To eliminate any transmit signal from appearing at the received signal input, the second term in the above equation must be set to zero, giving :

$$(1 + R2 / R1) (2R4 / R3 + R4) = R2 / R1$$

Solving for R3 / R4:

$$R3 / R4 = 1 + 2R1 / R2$$

Additionally,

$$G_R = R2 / R1$$
 and $G_T = R6 / R5$

These equations can be solved to select component values that meet the desired requirements. For example, if the transmit and receive loss in the coupling transformer is 2.5 dB, then:

$$R2/R1 = INV Log (G_{RdB}/20) = INV Log (2.5/20) = 1.333$$

Similarly,
$$R6 / R5 = 1.333$$
 and $R3 / R4 = 2.5$

Some typical values are:

It should be noted that the transmit amplifier is only needed to overcome the loss in line coupling. It can be eliminated since the transmit signal level specification is typically stated as a maximum. Amplifier B, resistors R5 and R6, and capacitor C1 can be eliminated, and point X can be connected to point Y in the circuit of figure 2 to achieve a more cost effective external hybrid arrangement.

The SC11024 with the internal hybrid may also be used on 4-wire system where the transmit and receive signals are kept separate. In this mode, the "Hybrid" code must be turned off. The transmit signal is connected to a 600 ohm line transformer through a 600 ohm resistor.

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The tone generator section consists of a DTMF generator, V.22 guard tone, and 1300 and 2100 hz tone generators. The DTMF generator produces all of the tones corresponding to digits 0 through 9 and A, B, C, D, *, and # keys. The V.22 guard-tone generator produces either 55 Hz or 1800 Hz. Selection of either the 550 Hz or 1800 Hz tone will cascade the corresponding notch filter with the low-band filter. The tones are selected by applying appropriate codes through the tone control register. Before a tone can be generated, tone mode must be selected. Facility is also provided to generate single tones corresponding to 1300 and 2100 Hz and the individual rows and columns of the DTMF signal.

Audio Output Stage

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A programmable attenuator that can drive a load impedance of 50 KOhms is provided to allow monitoring of the received line signal through an external speaker. The attenuator is connected to the output of the hybrid. Four levels of attenuation no attenuation, 6 dB attenuation, 12 dB attenuation and squelch are provided through the ALC1 and ALC0 audio output level control codes. Output of the attenuator is available on the audio output pin where an external audio amplifier (LM386 type) can be connected to drive a low impedance speaker. The output can directly drive a high impedance transducer, but the volume level will be low.

Clock Input

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CLKIN (Pin 22) of the SC11024 should be connected to a 9.8304 MHz clock source with an accuracy of $\pm 0.01\%$.

FUNCTIONAL DESCRIPTION OF THE SC11019 AND SC11020 CONTROLLERS

The SC11019 modem controller, implemented in IST's proprietary CMOS process, was designed specifically to handle all of the modem control functions, as well as the interface to a system bus. Besides including a 16-bit microprocessor, 16-bit microprocessor, 16K bytes of ROM and 320 bytes of RAM, it also contains the functionality of a 16C450 UART, greatly simplifying the interface to a parallel system bus such as the one used in IBM's PC. In fact, a complete, Hayes compatible modem for the PC consists of the SC11019 controller, the SC11024 modem and the DAA. All of the popular communications software written for the PC will work with the SC11024 / SC11019 set.

Another version of the controller, the SC11020, is intended for RS-232 applications. It contains the processor, memory, and UART as the SC11019 and has the same interface to the modem chip. The

difference is that the UART is turned around so that the serial data from the RS-232 port is converted to parallel data handled by the internal processor. Pins are provided for connecting the familiar switches and indicator lamps found on most stand-alone modems, although the switches and lamps are not needed for operation - all of the switch settings can be done through software.

The controller receives an 8-bit signal sample for the SC11024 and performs adaptive equalization, carrier phase recovery, data decode, and descrambling. SC11019 and SC11020 have identical hardware. Each controller can be configured as an SC11019 or SC11020 by the software. The controller is designed by using a 16-bit 2900 - type bit slice processor to perform the digital signal processing and the control functions. Its instruction set is a subset of the Intel 8096 instruction set, which operates faster than the 8096.

The SC11020 provides a standard 5 V logic level interface - RS-232 drivers are required to interface to the port. Like the SC11019, the SC11020 comes programmed with the Hayes "AT" command set, and when used with the SC11024 modem, emulates a Hayes - type standalone modem. The SC11019 and SC11024 emulate a Hayes - type IBM PC plug - in card modem.

But the chip set is by no means limited to implementing a Hayes type smart modem. IST is in the custom IC business and both chips were designed with this in mind. For example, only about 15 kbytes of the SC11019's ROM is used for the handshaking and smart modem code, leaving 1 kbytes for additional features that a customer may specify. And since the controller is ROM programmable, any command set, not just the Hayes "AT" set, can be implemented.

Both the SC11019 and SC11020 are available in two pin out options. They are 48 pin DIP, and 44 pin PLCC. The 44 pin version of SC11019 is programmed to support a different modem (SC11006) and is not recommended for use with SC11024. The 44 pin version programmed for SC11024 is SC11023CV.

The SC11021 is a ROM less version of the SC11019 & 20. It is available in a 68 pin PLCC and operates with up to 32 k external ROM. It can be configured for either serial or parallel operation.

A fourth version, SC11022, is available in 48 pin DIP and 68 pin PLCC. This version can be configured as either a serial or a parallel modem and in the 68 pin package, it can also address up to 24 k external ROM

Please refer to SC11019 series data sheet for complete details on controller features and performance characteristics.

Both the controllers require +5 V power supply. Besides the interface for the SC11024 modem, the SC11019 controller has an eight-bit data port, three address lines, a chip select input, an interrupt line, and the DOST and DIST control lines found in the 16C450 UART. It also has control lines for ring indication, the off-hook relay and a data / voice relay; these lines connect to the DAA.

In the SC11020, the eight-bit port becomes the switch input lines, and I / O port, and the address chip

select, INTO, DIST and DOST lines become the lines for the RS-232 interface and modem status. These lines are also used to drive the LEDs. Internally, all of these lines are treated as programmable I / O ports under software control - so the main difference between the SC11019 and SC11020 is the ROM code. It also contains the same modem and DAA interface lines as the SC11019

The interface to the SC11024 is via an 8-bit address / data bus and the control lines for read and write. The same interface is used for access to an electrical erasable random access memory (SC22201). There are six clock multiplexed address / date bus cycles. A ready signal is provided from the interface to a high speed PC - AT type bus cycle. For the 68 pin packages, there are 15 extra address lines and chip selects for external ROM and external RAM interfaces. An EA pin is also available for selection of internal ROM or external ROM.

The SC11019 and SC11020 are truly ASIC controllers - they are designed to control a modem or other peripheral that operates at a moderately slow data rate up to 2400 bits per second. What's unique about the SC11019, for example, is that it allows a slow peripheral to interface to a high speed bus without making the main processor add unnecessary wait states.

This is done through the UART interface and on the on-chip registers which look somewhat like dual port registers. The main processor can write to and read from them at will, while the on-chip controller can do the same. The controller was designed this way because most communications software has to have unrestrained access to the UART registers. To make the SC11019 compatible with the software, the registers were included.

The internal processor monitors the registers to determine the mode of operation - command mode or data mode, at power-up, it is automatically put in the command mode and it looks for instructions. Once carrier is detected, it goes into the data mode, and stays there until an escape sequence is entered, just like a Hayes type modem. The escape sequence is three + signs -+++- in the default mode, but it can be changed in the software.

The actual processor contains a 16-bit data path and can execute 54 instructions with three different addressing modes: direct, indirect and immediate. There is 16 k or 8 of ROM on the chip for program storage.

To the system bus, the SC11019 looks and acts like a 16C450 UART. Communications software written for this UART will work with the SC11019 and SC11020. The IST chip set is truly a Hayes type modem in two chips.

THE SC11024 & SC11019 / SC11020 SYSTEM

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The only external components required by the SC11024 are a 560 Ohm line matching resistor and a 1.0 μ F capacitor from the EDC pin to ground. That's all ! If it is desired to drive a speaker to monitor the line, an amplifier like the LM386 can be added, but the output provided on the SC11024 can directly drive a high impedance (50 kohm) earphone type transducer.

The SC11024 modem's CLKIN pin line is driven by the SC11019 CKOUT line at 9.8304 MHz. The SC11019 interfaces directly to an IBM PC bus. External perts required will be an LS245 to drive the bus and an LS30 and L804 for COM1 / COM2 decoding. A ready signal is provided to control the IOCHRDY pin on the bus to allow operation with higher speed computers (AT, XT TURBO, etc.)

For tone dialing, the controller sends a code to the modem chip which in turn puts out the required DTMF tones on the line via the on chip DTMF generator. For pulse dialing, the controller pulses the OH (off-hook) relay. Both dialing modes work with the built-in call progress algorithm so they can't delay dialing until a dial tone is detected.

All modems require a DAA. A DAA or data access arrangements is a line interface required by the FCC to connect anything to the general switched telephone network. It consists of an isolation transformer, typically 600 ohms to 600 ohms; a relay for disconnecting the modem from the line; a ring detector, typically an optoisolator; and high voltage surge protectors. The DAA has to be FCC registered and this can be done by one of many consultants labs around the country. The fee is typically \$2,000 and it takes several weeks. Another alternative to buy an approved DAA, supplied by several manufacturers. This covers part 68 of the FCC spec, but the modem will still be required to pass part 15 radiation tests.

V.22 bis is a CCITT specification that calls for 2400 bps, full or half duplex data transmission with a fallback mode of 1200 bps. It is not 2400 baud; the spec calls for transmission of quad bits - 4 bits per baud so the 2400 bps transmission takes place at 600 baud. The same is true for V.22 - it is 12 bps or 600 baud. V.22 does not call for a 300 baud fallback; there is a CCITT standard for 300 bps and that's V.21

V.22 and V.22 bis also call for guard tones to be sent along with the data. In most of Europe the tone is 1800 Hz except in Sweden where 550 Hz is used. The SC11024 modem has the 550 Hz and 1800 Hz tone generators built in as well as the 550 and 1800 Hz notch filter to remove the guard tone in the receiver.

All modems require a Hybrid; a term used to describe a circuit, passive or active, that takes the separate transmit and receive signals and combine them for the phone line. In the SC11024, this is done with onchip op amps. The internal hybrid can be disabled so an external hybrid can be used, if desired.

CONNECTION DIAGRAM FOR CONTROLLERS

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PIN DESCRIPTIONS

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PIN NO.	PIN NAME	DESCRIPTION
1	SCR	Synchronous Clock Receive (Data set source); Output; TTL; Used only in bit synchronous mode; recovered by the Receiver Phase Locked Loop from the far end modem. Data or RXD is valid at the rising edge of this clock.
2	V _{REF}	Reference Ground; Generated inside the chip and is equal to $V_{CC}/2$
3	SCT*	Synchronous Clock Transmit (Data Set Source); Output; TTL; Used only in bit synchronous mode; Generated internally by the SC11024 Clock Generator; Rate = 1200 Hz, ±0.01% or 2400 Hz ±0.01%
4	SCTE	Synchronous Clock Transmit External (DTE source); Input TTL; Used only in bit synchronous mode; Data on TXD line is latched by the SC11024 at the rising edge of this clock. Clock rate = 1200 Hz $\pm 0.01\%$ or 2400 Hz ± 0.015
5	AUDIO	Audio Output; The hybrid output is passed through a programmable attenuator and fed to this analog pin. Four different levels can be attained by controlling bit 0 and bit 1 of the AUDIO register as specified under AUDIO register description
6	EDC	Capacitor for energy detect; A1.0 µF capacitor should be connected between this pin and AGND
7	DGND	Digital ground
8	CS	Chip Select; Input; TTL; Active low
9	WR	Write; Input; TTL; Normally high; Data on AD7 - AD0 is written into the SC11024 registers at the rising edge of this pulse.
10	RD	Read; Input; TTL; Normally high; Data on AD7 - AD0 is to be read by the processor at the rising edge of this pulse
12, 13, 17, 18	AD1 - AD4	Multiplexed address / data bus (8-bits); Input / Output; TTL; A/D4 - A/D1 (4 bits) are used for multiplexed addressing of internal registers.
14	AGND	Analog ground
15	RXA	Receive analog; Input
16	TXA*	Transmit analog; Output
11, 19-21	D0, D5 - D7	Bits 0, 5, 6 and 7 don't care as far as address is concerned.
22	CLKIN	Clock input 9.8304 MHz clock input for the controller.
23	GS	Gain select to compensate for loss in line coupling transformer. When left open or tied to AGND, the compensation is 0 dB; connected to V_{REF} , +2 dB compensation is provided; And when tied to V_{CC} , the compensation is +3 dB

24	ALE	Address Latch Enable; Input; TTL; The address on A/D4 - A/D1 is latched into the SC11024 Address decoder at the falling edge of this normally low pulse
25	INT	Interrupt; Output; TTL; Normally low; A short (13 µs typical) positive pulse is generated after A to D conversions are completed.
26	RXD*	Received Data; Output; TTL
27	TXD	Transmit Data; Input; TTL
28	V _{CC}	+5 V supply

*1.6 nA drone

REGISTERS

There are twelve 8-bit registers interfacing to the microprocessor bus. Five of these registers can only be read by the processor (called READ registers) and the remaining seven can be written into by the processor (called CONTROL registers). Bit 1 of the "Tone" register can be read and written by the processor. Table 1 shows the address and bit assignments for these registers.

A chip select pin is provided for multiperipheral addressing by the processor.

ADDRESS BITS NAME MSB BIT NUMBER LSB A4 **A3** A2 7 6 5 4 3 2 1 **A**1 0 Q17 Q13 Q12 0 0 0 0 Q1 Q16 Q15 Q14 Q11 Q10 1 0 0 0 **I**1 I17 I16 I15 I14 I13 I12 I11 I10 0 0 1 0 Q22 Q20 Q2 Q27 Q26 Q25 Q24 Q23 Q21 12 0 1 1 I27 I26 I25 I24 I23 I22 I21 0 I20 X X X **FSKD** 0 1 0 0 Status **AGCO** PA PR ED X 1 Unused Unused 0 1 Unused 0 1 1 X Unused

Table 1. READ Registers

<u>Status Register</u> Control Register

STATUS Register: Address (A4 - A1) = 0100

BIT NUMBER BIT NAME	DESCRIPTION

Bits 7-5	Unused	
Bit 4	AGCO	Status of internal 1-bit AGC. When this bit is set, RXA signal is amplified by 8 dB before entering the band pass filters.
Bit 3	PA	This bit is set whenever the clock recovery DPLL advances one step (skips a count) to lock. It is cleared only when STATUS register is read.
Bit 2	PR	This bit is set whenever the clock recovery DPLL retards one step (adds an extra count) to lock. It is cleared only when STATUS register is read.
Bit 1	FSKD	Received FSK data. FSKD = 1 when mark is received.
Bit 0	ED	Energy detect circuit output. ED = 1 when energy detected.

Note 1: When DPLL neither advances nor retards, then PA = PR = 0.

Note 2 : When reading unused bits, the corresponding bus lines will not be driven by the SC11024 and will be floating.

Table 1a. READ Registers

Q1 Register :	Stores mid baud inphase sample output of ADC
I1 Register:	Stores mid baud quadrature sample output of ADC
Q2 Register :	Stores end baud inphase sample output of ADC
I2 Register:	Stores end baud inphase sample output of ADC

Note: All samples are represented in two's complement from

Table 2. **CONTROL Registers**

A	DDI BI	RES TS	S	NAME	BIT NUMBER							
A4	A3	A2	A1		7	6	5	4	3	2	1	0
1	0	0	0	TXCR	BR7	HYBRID	TXSEL2	TXSEL1	TXSEL0	SQT	BR1	BR0
1	0	0	1	MCRA	X	LCK / INT	RNGX	SYNC	WLS1	WLS0	A/O	RXMRK
1	0	1	0	MCRB	BR3	PD	X	CPM	ALB	TL2	TL1	TL0
1	0	1	1	TONE	X	HNDSHK	TONEON	DTMF	D3	D2	D1	D0
1	1	0	0	PGCR	X	AGCVT	G5	G4	G3	G2	G1	G0
1	1	0	1	DATA	X	PLLJAM	PLLFRZ	PLLFAST	RD3	RD2	RD1	RD0
1	1	1	0	AUDIO	X	DISS	PGCZ	TST2	TST1	TST0	ALC1	ALC0
1	1	1	1					UNUSED				

Transmit Control Register (TXCR): Address (A4 - A1) = 1000 (Note : When writing into these registers, the bus lines corresponding to the unused bits are ignored by the SC11024)

BIT NUMBER	BIT NAME	DESCRIPTION						
Bit 7	Unused							
Bit 6	HYBRID							
Bit 5	TXSEL2 and	When set, the transmitter output (TXA) is connected to the inverting input of the receive buffer to allow the use of the on-chip hybrid circuit for 2 to 4 wire conversion.						
Bit 4	TXSEL1 and	Transmi			B bits determine the data transmitted by the ording to the following table:			
		TXSEL2	TXSEL1 0	TXSEL0	TRANSMITTED DATA External data sent by DTE.			
		0	0	1	Unscrambled S1 (Note 1).			
	TXSEL0	0	1	0	Unscrambled Space.			
		0	1	1	Unscrambled Mark.			
		1	0	0	Scrambled RX. Digital loop back mode (Note 2).			
		1	0	1	Scrambled Reversals (Note 3 and 4).			
Bit 3		1	1	0	Scrambled Space (Note 4).			
		1	1	1	Scrambled Mark (Note 4).			
		Note 1: S1 is a pattern of 0011 transmitted at 1200 bps rate regardless of BR1. If in FSK mode (BR = 1), then reversals are sent. This pattern cannot be sent at 2400 bps rate. Note 2: In this mode, the received data, after being descrambled, is sent back to the scrambler. The modem will automatically go to the Synchronous mode with Slave timing. Note 3: Reversals are continuous streams of 01. Note 4: When in FSK mode (BR0 = 1), TXSEL2 is ignored since scrambling is not applicable.						
Bit 2	SQT	When thi			nitter is squelched by connecting the output the block diagram) to V_{REF} .			

Bit 1	BR1 and	Bit rates Selection bits based on the following table:					
		BR3	BR2	BR1	BR0	BIT RATE	
Bit 0	BR0	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	0	0	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	2400 bps V.22 bis 1200 bps V.22 / 212A	
		0	0	0	1	0 - 300 bps Bell 103	
		0	0	1	1	0 - 300 bps CCITT V.21	

Mode Control Register A (MCRA) : Address (A4 - A1) = 1001

BIT NUMBER	BIT NAME	DESCRIPTION
Bit 7	Unused	
Bit 6	LCK / INTB	Determine the clock source for the transmitter. When this bit is set, the clock source is externally provided on SCTE (pin 40, and when cleared, it is externally generated (SCT). This bit can select the clock source independent os Sync / Async mode selection (see below). When in Digital Loop-Back mode, the clock source will be forced to the Slave mode (SCR).
Bit 5	RNGX	Range extender for the receiver Sync / Async converter. When set, the receiver Sync / Async can insert up to one stop bit per four (8, 9, 10 or 11-bit) characters to compensate for a far end DTE being up to 2.3% over speed. The transmitter Sync / Async always handles this over speed condition regardless of this bit's condition.
Bit 4	SYNC	When set, operate in bit synchronous mode; when clear, operate in character asynchronous mode. When in Digital Loop-back mode, the SC11024 will be forced to the Synchronous mode.
Bit 3	WLS1 and	Word length select bits in asynchronous mode, according to the following table:

		WLS1	WLS0	NUMBER OF BITS PER CHARACTER	
		1	0	8	
Bit 2	WLS0	1	1	9	
		0	0	10	
		0	1	11	
Bit 1	A/O	When set, operate in answer mode; when clear. operate in originate mode.			
Bit 0	RXMARK	When set, the RXD pin is clamped to the high logical level.			

Mode Control Register B (MCRB) : Address (A4 - A1) = 1010

BIT NUMBER	BIT NAME	DESCRIPTION
Bit 7	Unused	
Bit 6	PD	When this bit is set, chip will be powered down. When cleared, chip will go into normal power mode.
Bit 5	unused	
Bit 4	СРМ	Call progress monitor mode. When set, the receiver path can be connected to the high band filter to detect answer tone (ALB = 0) or to the low band filter scaled down 2.5 times (ALB = 1) to listen for the call progress tones during auto dialing.
Bit 3	ALB	Analog Loop Back. When set, the transmitter output (TXA) is connected to the receive path, bypassing the receive filter.
Bit 2	TL2 and	Transmit level adjust bits based on the following table:
Bit 1	TL1 and	

		TL2	TL1	TL0	TRANSMIT LEVEL AT TXA PIN
		0	0	0	-3 dBm
		0	0	1	-5 dBm
		0	1	0	-7 dBm
Bit 0	TL0	0	1	1	-9 dBm
		1	0	0	-11 dBm
		1	0	1	-13 dBm
		1	1	0	-15 dBm
		1	1	1	-17 dBm

TONE Register Address (A4 - A1) = 1011

BIT NUMBER	BIT NAME						DESCR	IPTION					
Bit 7	Unused												
Bit 6	HNDSHK		This bit is set only during handshaking sequence. When set, both FSK and PSK / QAM demodulators are enabled. When cleared, FSK demodulator is disabled when in high speed mode.										
Bit 5	TONEON	When	When set, the output of the tone generator appears at TXA. When cleared, the output of the tone generator is squelched.										
Bit 4	DTMF*	Wher	When set, the DTMF generator is turned on. WHen cleared, the DTMF generator is turned off, but other tones can be generated.										
				Spe	cify	the	desired tone (see the followi	ng table) :				
		DTMF	D3	D2	D1	D0	DIGIT DIALED	TONE OUTPUT	FREQUENCIES (HZ)				
		1	0	0	0	0	0	941	1336				
		1	0	0	0	1	1	697	1209				
		1	0	0	1	0	2	697	1336				
		1	0	0	1	1	3	697	1477				
		1 0 1 0 0 4 770 1209											
		1	1 0 1 0 1 5 770 1336										

		п									
		1	0	1	1	0	6	770	1477		
		1	0	1	1	1	7	852	1209		
		1	1	0	0	0	8	852	1336		
		1	1	0	0	1	9	852	1477		
Bit 3-0	D3 - D0	1	1	0	1	0	*	941	1209		
		1	1	0	1	1	(A)	697	1633		
		1	1	1	0	0	(B)	770	1633		
		1	1	1	0	1	(C)	852	1633		
		1	1	1	1	0	#	941	1477		
		1	1	1	1	1	(D)	941	1633		
		0	0	0	0	0	No to	one; tone genera	ator turned off		
		0	0	0	0	1		550			
		0	0	0	1	0		1800			
		0	0	0	1	1		2100			
		0	0	1	0	0		1300			
		0	0	1	0	1	No to	No tone; tone generator turned off			
		0	0	1	1	X	No tone; tone generator turned off				
		0	1	X	X	X	No to	one; tone genera	ator turned off		
		Note: TONEON must also be set to generate DTMF signals.									

Programmable Gain Controller Register (PGCR) : Address (A4 - A1) = 1100

BIT NUMBER	BIT NAME	DESCRIPTION
Bit 7	Unused	
Bit 6	AGCVT	When set, prevents gain hit due to AGC's gain step. This bit must be set during the handshaking after detecting the four point constellation and before switching to 16-way decision making.

		Control the gain of the PGC within a range from -10 to +37.5 dB in 0.75 dB steps. (See the following table):									
		G5	G4	G3	G2	G1	G0	PGC GAIN (dB)			
		0	0	0	0	0	0	-10.0			
		0	0	0	0	0	1	-9.25			
	G5 - G0	0	0	0	0	1	0	-8.5			
Bit 5-0		0	0	0	1	0	0	-7.0			
		0	0	1	0	0	0	-4.0			
		0	1	0	0	0	0	+2.0			
		1	0	0	0	0	0	+14.0			
		1	1	1	1	1	1	+37.25			
		Note:	_		•			tering the filter) by an internal us a fixed gain of 5 dB			

DATA Register : Address (A4 - A1) = 1101

BIT NUMBER	BIT NAME	DESCRIPTION
Bit 7	Unused	
Bit 6	PLLJAM	When this bit is set, the DPLL will be reset by the next raising edge of the received baud clock. This bit must remain high for atleast one baud period. It should be cleared by the processor to end the jamming mode. PLLFRZ (see below) overrides PLLJAM when both are enabled.
Bit 5	PLLFRZ	Phase locked loop freeze. When this bit is set, the DPLL begins to run freely regardless of the received baud clock. To re-enable the DPLL locking, the bit must be cleared by the processor PLLFRZ overrides PLLJAM when both are enabled.
Bit 4	PLLFAST	When set, the DPLL operates in "fast" locking mode. In this mode, the DPLL is updated on every baud period by 13 µs steps. When this bit cleared (default mode), the DPLL operates in "normal" locking mode and is updated once every 8 baud periods by 6.5 µs steps.

Bit 3-0	RD3 - RD0	asynchronous mode. RD0 is the first bit appearing on the RXD pin, followed by RD1, RD2 and RD3. In the 1200 bps mode, only RD0 and
		RD1 are shifted out during one baud period

AUDIO Register : Address (A4 - A1) = 1110

BIT NUMBER	BIT NAME			DESCRIPTION						
Bit 7	Unused									
Bit 6	DISS		Transmit select bits (TXSEL0 - 2) override this bit when in "transmit internal mode".							
Bit 5	PGCZ		When set the output of the PGC is grounded. DC offset of the demodulator can be stored and cancelled by the controller.							
Bit 4-2	TEST	Test bits	Test bits used for factory testing. For normal chip operation, these bits must be cleared.							
Bit 1	ALC1	Audio level control bit 1.								
				DIO pin according to the following table:						
		ALC1	ALC0	AUDIO ATTENUATION (dB)						
		0	0	Audio off						
Bit 0	ALC0	0	1	12						
		1	0	6						
		1	1	0 (no attenuation)						
		Note: The	•	al may be amplified by 12 dB by the time receiver fore being fed to the audio attenuator.						

SYNCHRONOUS OPERATION

Transmitter Timing

Case 1 - SC11024 Provides the Timing to the Data Terminal Equipment (DTE) See Figure 3.

If the DTE can look to an external clock, then all that needs to be done is to put the SC11024 in the

synchronous mode. This provides a 2400 / 1200 Hz clock on the SCT pin that can be used as a clock source for the DTE. The Transmit Phase - Locked - Loop (TX PLL) of the SC11024 will be in the free running mode.

Case 2 - SC11024 Should Lock its Transmit Timing to the Clock Source Provided by the DTE. In this case after selecting synchronous mode, also select "Locked" mode.

The TX PLL od SC11024 will then synchronize itself to the clock provided on its "SCTE" pin.

Case 3 - Slave mode. The Transmit Timing is slaved to the receiver recovered clock. Select synchronous mode and connect SCTE to SCR.

In either case, the SC11024 will sample the data on the rising edge of the clock.

Receiver Timing

In synchronous mode, the recovered clock will be provided on the SCR pin and the transitions of RXD will be on the falling edges of this clock. Data is valid on the rising edge of the clock.

SYNCHRONOUS MODE CHART

Transmitter Timing

SPECIFICATIONS

Absolute Maximum Ratings

Operating Conditions

DC Electrical Characteristics

AC Electrical Characteristics

Modem Transmit Signals -Hz

DTMF Generator

Absolute Maximum Ratings (Notes 1 - 3)

Supply Voltage, V _{CC} -GND	7 V
DC Input Voltage (Analog Signals)	AGND -0.6 to V _{CC} +0.6 V
DC Input Voltage (Digital Signals)	DGND -0.6 to V _{CC} +0.6 V
Storage Temperature Range	-65 to 150 ^O C
Power Dissipation (Note 3)	500 mW
Lead Temperature (Soldering 10 Sec)	300°C

Operating Conditions

PARAMETER	DESCRIPTION	CONDITIONS	MIN	TYP	MAX	UNITS
T_{A}	Ambient Temperature		0		70	OC
V _{CC}	Positive Supply Voltage		4.5	5.0	5.5	V
AGND, DGND	Ground			0		V
F _C	Clock Frequency		9.8295	9.8304	9.8313	MHz
T_R, T_F	Input Rise or Fall Time	All digital inputs except CLKIN			500	ns
T_R, T_F	Input Rise or Fall Time	CLKIN			20	ns

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DC Electrical Characteristics ($T_A = 0$ TO 70° C, $V_{CC} = +5$ V $\pm 10\%$)

PARAMETER	DESCRIPTION	CONDITIONS	MIN	TYP	MAX	UNITS
I_{CC}	Quiescent Current	Normal		17	25	mA
1CC	Quiescent Current	Power Down Mode		1.0	4	mA
V _{IH}	High Level Input Voltage;		2.4			V
TH	Digital pins		2.4			•
V_{IL}	Low Level Input Voltage;				0.8	V
·IL	Digital pins				0.8	•
V _{OH}	High Level Output		2.4			V
OH	$(I_{OH} = 0.5 \text{ mA})$		2.4			•
V _{OL}	Low Level Output				0.6	V
, OL	$(I_{OL} = 0.5 \text{ mA})$				0.0	•
VXTA	Maximum Peak Output Level on TXA	$V_{CC} = +5 \text{ V}$	3			V_{PP}
VAIA	pin	100-13				Y PP

- Notes: 1. Absolute maximum ratings are those values beyond which damage to the device may occur.

 2. Unless otherwise specified, all voltages are referenced to ground.
 - 3. Power dissipation temperature derating Plastic package : -12 m W / C from 65^OC to 85^OC.

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PROCESSOR BUS TIMING

When the controller is reading or writing to the SC11024, the address must be valid atleast 30 ns before ALE goes low and stay valid 40 ns or more.

When the controller is writing, data must be valid at least 40 ns before WR goes false and stay valid until at least 0 ns after WR goes false.

When reading from the MAP, data is valid a maximum of 185 ns after RD goes true and stays valid at least until 0 ns after RD goes false.

AC Electrical Characteristics

	SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
1	TAVEL	Address Valid to ALE low		30			ns
2	THAD	Hold address after ALE low		40			ns
3	TALRD	Delay from ALE low to RD low		45			ns
4	TDVRL	Data valid after RD low				180	ns
5	TRD	Read pulse width		200			ns
6	TDHRD	Data hold after RD high		0			ns
7	TWR	Write pulse width		150			ns
8	TDVWR	Data setup before WR high		70			ns
9	TDHWR	Data hold after WR high		15			ns
10	TRHLH	End of read to next ALE		55			ns
11	TWHLH	End of write to next ALE		120			ns
12	TDVRH	Data valid set- up to RD high		15			ns
13	TMCAL	MCS low to ALE high		10			ns
14	TALE	ALE Pulse width		40			ns

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Modem Transmit Signals - Hz (Assume 9.8304 Crystal)

PARAMETER	CONDITIONS	MON.	ACT.	UNITS

FSK Mod / Demod Frequencies

Bell 103			
Answer Mark	2225	2226	Hz
Answer Space	2025	2024.4	Hz
Originate Mark	1270	1269.4	Hz
Originate Space	1070	1070.4	Hz

CCITT V.21

Answer Mark	1650	1649.4	Hz
Answer Space	1850	1850.6	Hz
Originate Mark	980	978.34	Hz
Originate Space	1180	1181.53	Hz

Call progress monitor mode:

		MIN	TYP	MAX	
Center frequency	ALB = 1, G5 - G0 = 110111		480		Hz
Detect level (ED high) measured at RXA		-43			dBm
Reject level (ED low) measured at RXA				-48	dBm
Hysterisis measured at RXA		2			dB
Delay time (ED low to high)	$EDC = 1.0 \mu F$	10	15	24	ms
Hold time (ED high to low)	EDC = 1.0 μF	10	15	24	ms

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DTMF Generator (Note 1)

PARAMETER	NOMINAL FREQUENCY	ALLOWABLE ERROR	ACTUAL ERROR
Row 1	697 Hz	±1%	-0.23%
Row 2	770 Hz	±1%	-0.01%
Row 3	852 Hz	±1%	-0.12%
Row 4	941 Hz	±1%	-0.39%

Column 1	1209 Hz	±1%	-0.35%
Column 2	1336 Hz	±1%	-0.93%
Column 3	1477 Hz	±1%	-0.48%
Column 4	1633 Hz	±1%	-0.91%
Guard Tones	550 Hz	±20 Hz	-2 Hz
Guard Tones	1800 Hz	±20 Hz	-2 Hz
Calling Tone	1300 Hz		-6 Hz
Answer Tone	2100 Hz		+1 Hz

DTMF Generator

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Second Harmonic Distortion			-40		dB
Row Output Level	VCC = +5 V		-2		dBm
Column Output Level			0		dBm
550 Hz Guard Tone	TL2 = TL1 = TL0 = 0		-6		dB (Note 2)
1800 Hz Guard Tone	Measured at TXA Pin		-9		dB (Note 2)
1300 Hz Calling Tone			-3		dB
2100 Hz Answer Tone			-3		dB
Transmit level measured at TXA	Load = 1200 Ohms $TL2 = TL1 = TL0 = 0$ $Squelched$		-3	-50	dBm dBm

Notes: 1. This assumes a clock of exactly 9.8304 MHz.

2. These levels are referenced to the TX signal level. When guard tones are added, the TXA level is adjusted to maintain a constant level on the line. For 1800 Hz, the adjustment is -0.97 dB, for 550 Hz the adjustment is -1.76 db, per the CCITT specifications.

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
Data Mode	EDC = 1.0 μF; measured at RXA PGC = 0				
Energy detect level (ED low to high)				-43	dBm
Loss of energy detect level (ED low to high)		-48			dBm
Hysterisis		2	3		dB

Programmable Gain Controller (PGC)

Gain step size	0.75 dB
Dynamic range	47.25 dB
Response time (from change in PGC register to output of A to D converter)	1.0 ms

Filter Characteristics

Cross talk rejection	70	dB
Power supply rejection	0	dB
DPLL Response times JAM or FRZ Fast	20 200	μs μs

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APPLICATION INFORMATION

Top

Applications

The SC11024 with an external control microprocessor, a telephone line interface and a suitable computer interface, can implement a complete 2400 bps modem for many applications with a minimum of components and cost. Figure 7 shows the common portion of such a modem using the SC11024 with a telephone line interface. IST's SC22201, 128 byte E^2 memory is used to store default parameters and often used phone numbers. The SC11019 / 20 / 21 / 22 / 23 controllers also support a serial E^2 memory as an alternative. Figure 6 and 7 show the stand alone and PC bus integral modems implemented with IST's SC11019 / 20 controllers. Figure 8 shows the connections for an internal ROM special purpose controller using the SC11022. Figure 9 shows an RS-232C serial interface for implementing a stand alone modem. Figure 10 shows a parallel bus interface for implementing an internal modem for an IBM PC / XT / AT compatible computer when used with IST's 11019 controller shown in figure 6, while Figure 13 shows the interface required for implementing the same internal modem when used with the controller shown in figure 12. Figure 11 shows a power supply schematic for a stand alone modem application.

Various modem configurations can be realized by combining schematics shown in Figure 5 through 13.

A Hayes compatible stand alone smart modem (Fig 5) can be implemented by combining Figures 7, 8, 9 and 11.

The internal version for an IBM PC / XT / AT compatible (Figure 6) can be implemented using Figures 7, 8 and 10.

An alternative to the controller of Figure 8 is shown in Figure 12 and 13.

For performance evaluation, a circuit is shown in Figure 14 can be used to obtain a constellation of the modem. Quality of the signal processing performed by the modem can thus be visualized by observing the constellation for various line conditions and signal to noise ratios.

Power Supply Decoupling and Circuit Layout Considerations

For optimum performance at low received signal levels with low S / N ratios, it is important to use the recommended power supply decoupling circuit as shown in Figure 7.

Small inductors in series with the supplies help suppress RFI as well as improve the power supply noise rejection capability of the SC11024. A 10 ohm, 1/4 W resistor in place of, or in series with, the inductor in the SC11024 power lead has been found to be helpful in computer based products or where the power supply is particularly noisy.

The 10 μ F capacitor should be a tantalum type while the 0.1 μ F capacitors should have good high frequency rejection characteristics - monolithic ceramic types are recommended. It is important to locate the decoupling capacitors as close to the actual power supply pins of the SC11024 as possible. It is also recommended that the analog ground and digital ground buses be routed separately and connected at the common ground point of the power supply.

A Ferrite bead on the 5 V input to the circuit board should also be considered, both from a modem performance stand point, as well as an aid in reducing RF radiation from the phone line.

NOTE: Crystal oscillator: The controller requires a parallel resonant 19.6608 MHz crystal designed with CL = 18 pF and tolerance of $\pm .01\%$ (such as Saronix NYP196 - 18). With this crystal, use 27 pF to ground from both XTAL1 and XTAL2. Clock frequency measured at CKOUT (Pin 7) must be within $\pm 0.01\%$ of 9.3804 MHz.

CONFIGURATION FOR SC11019CN, 20CN, 20CV, 22CV BIG MACS

All models listed above can operate with either serial or multiplexed EEPROMs for configuration and number storage. The internal ROM program automatically determines which kind of EEPROM is connected and adapts accordingly.

Note that the SC11022 pin configuration matches that of the SC11011 controller except five new pins are used that were formerly not connected. Four of these are the I / O pins described above. One is the

TDOUT pin which is used with SC11026 for V.23 signaling. For upward compatibility the TDOUT pin may be permanently wired to TXD.

When substituting SC11022 for SC11011 it is only necessary to open the EA pin and remove the external EPROM. Connect the jumpers as shown if required to operate with SC11024 MAP, external hybrid or in serial mode.

Three of the four I / O pins on the specified model of the internal ROMed MAC are programmed to set the configuration at power up or reset. Internal weak pull-up resistors will set the default configuration to internal hybrid, ± 5 V SC11006 MAP interface and Parallel mode if there is no external pull down.

External pull down resistors must be added to select other options as indicated in the table. The I / O drivers will overcome these pull-up or pull down resistors in normal operation to operate the serial EEPROM. The I / O pins may be directly grounded if the serial EEPROM is not used.

In the 44 - pin version of SC11019, the I/O pins are not externally available. The SC11023 is internally bonded to select the 5 V only MAP (SC11024) configuration.

MAC PART NO.	PACKAGE	INT. ROM	EXT. ROM	UART MODE	MAP
SC11019CV	44 - PLCC	16 k	-	Parallel	SC11006
SC11019CN	48 - DIP	16 k	-	Parallel	SC11006 / 24
SC11020CV	44 - PLCC	16 k	-	Serial	SC11006 / 24
SC11020CN	48 - DIP	16 k	-	Serial	SC11006 / 24
SC11021CV	68 - PLCC	0	24 k	Serial / Parallel	SC11006 / 24
SC11022CV	68 - PLCC	16 k	24 k	Serial / Parallel	SC11006 / 24
SC11022CN	48 - DIP	16 k	-		SC11006 / 24
SC11023CV	44 - PLCC	16 k	-	Parallel	SC11024

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