MATH 231A Solutions to PS 15

This matrix has just one eigenvalue $\lambda = 0$ of multiplicity two, and this eigenvalue is deficient because it yields just one linearly independent eigenvector $\boldsymbol{\xi} = (1, 2)$. Thus, one solution of the system $\mathbf{x}' = A\mathbf{x}$ is

$$\mathbf{x}^{(1)}(t) = e^{0 \cdot t} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

We need to find a second solution of the form $\mathbf{x}^{(2)}(t) = e^{0 \cdot t}(\boldsymbol{\eta} + t\boldsymbol{\xi}) = \boldsymbol{\eta} + t\boldsymbol{\xi}$, where $(A - 0I)\boldsymbol{\eta} = A\boldsymbol{\eta} = \boldsymbol{\xi}$. That is,

$$\left\{ \begin{array}{lll}
 4\eta_1 - 2\eta_2 &=& 1 \\
 8\eta_1 - 4\eta_2 &=& 2
 \end{array} \right\} \qquad \Rightarrow \qquad 4\eta_1 - 2\eta_2 &=& 1 \qquad \text{(same equation)} \\
 \Rightarrow \qquad \eta_2 &=& 2\eta_1 - \frac{1}{2}.$$

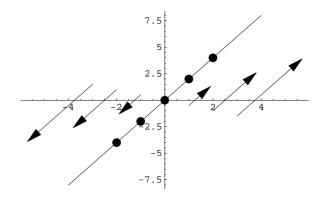
Taking $\eta_1 = \alpha$ (free), we have infinitely many such vectors $\boldsymbol{\eta}$, all of the form

$$\eta = \left(\alpha, 2\alpha - \frac{1}{2}\right) = \alpha(1, 2) + \left(0, -\frac{1}{2}\right).$$

We only need one such η , which will be result of choosing a particular value for β . The easiest thing is to take $\beta = 0$, which I will do in all future problems. To illustrate that any β is allowable, I will take $\beta = 1$ in this case, yielding $\eta = (1, 3/2)$. Thus, the general solution is

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \left[\begin{pmatrix} 1 \\ 3/2 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right].$$

Any particular solution with $c_2 = 0$, will remain (constantly) $c_1(1,2)$ — that is, if a solution begins along the line through the origin in the direction of (1,2), then it forever stays right where it started. (This line consists of only equilibrium points.) Solutions with $c_2 \neq 0$ (i.e., which do not start on the abovementioned line) do vary with time. However, all vary in precisely the same fashion moving in the direction of (1,2) if $c_2 > 0$ and in the



opposite direction if $c_2 < 0$. Those with a larger (in magnitude) choice of c_2 will move faster than those with a smaller c_2 . Thus, we get solution trajectories that appear as below (longer arrows correspond to faster-moving trajectories).

This matrix has the repeated eigenvalue $\lambda = -1$, also deficient in that it yields just one linearly independent eigenvector $\boldsymbol{\xi} = (2,1)$. The system of equations for $\boldsymbol{\eta}$ (what the book calls a generalized eigenvector) $(A+I)\boldsymbol{\eta} = \boldsymbol{\xi}$ can be written out as

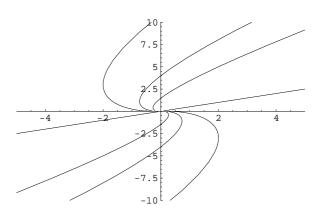
Taking η_2 to be free, and setting it equal to zero, we get $\eta = (-4,0)$. Thus, the general solution is

$$\mathbf{x}(t) = c_1 e^{-t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 e^{-t} \left[\begin{pmatrix} 0 \\ -4 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \end{pmatrix} \right].$$

From this general solution, we see that all solutions are attracted to the origin as $t \to \infty$. In particular, those solutions that begin on the line through the origin in the direction (2,1) (i.e., those solutions for which $c_2 = 0$), go straight along that line towards the origin (though they will take forever to get there). The solutions that start off this line (those which correspond to a nonzero c_2) have more interesting behavior. As $t \to \infty$, both parts of $\mathbf{x}^{(2)}$ become negligible. However, the term

$$c_2 e^{-t} \begin{pmatrix} 0 \\ -4 \end{pmatrix}$$
 dies off faster than $c_2 t e^{-t} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$.

Thus, such solutions asymptotically approach the previously-mentioned line as $t \to \infty$. If we follow such trajectories backward in time rather than forward (i.e., let $t \to -\infty$), then both terms of $\mathbf{x}^{(2)}$ grow exponentially. Nevertheless, $c_2t^e-t(2,1)$ still dominates the other term, and though such trajectories do not approach our previous line asymptotically as $t \to -\infty$, they do become more and more parallel to it.



This matrix has two eigenvalues: $\lambda = 2$ with its associated eigenvector (1, 1, 1), and $\lambda = -1$ (multiplicity 2) with two linearly independent eigenvectors (-1, 0, 1) and (-1, 1, 0) (so $\lambda = -1$ is *not* a deficient eigenvalue). Thus, the general solution is

$$\mathbf{x}(t) = c_1 e^{2t} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + c_2 e^{-t} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + c_3 e^{-t} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}.$$

This matrix has the repeated eigenvalue $\lambda = -3$, but is deficient, having just the one (representative) linearly independent eigenvector (1,1). There is, then, the need to find a solution of the form $e^{-3t}(\boldsymbol{\eta} + t(1,1))$. We seek $\boldsymbol{\eta}$ by solving $(A+3I)\boldsymbol{\eta} = (1,1)$:

$$\left. \begin{array}{rcl}
 4\eta_1 - 4\eta_2 &=& 1 \\
 4\eta_1 - 4\eta_2 &=& 1
 \end{array} \right\} \qquad \Rightarrow \qquad \eta_1 \ = \ \eta_2 + \frac{1}{4}.$$

Taking η_2 (free) to be zero, we have $\eta = (1/4, 0)$. Thus, the general solution is

$$\mathbf{x}(t) = c_1 e^{-3t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-3t} \begin{bmatrix} 1/4 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \end{bmatrix}$$
$$= e^{-3t} \begin{pmatrix} c_1 + c_2(t+1/4) \\ c_1 + c_2t \end{pmatrix}.$$

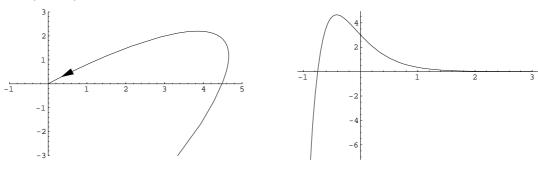
At time t = 0, we need this vector to be (3, 2), and so we solve

$$\left(\begin{array}{c} c_1 + (1/4)c_2 \\ c_1 \end{array}\right) = \left(\begin{array}{c} 3 \\ 2 \end{array}\right),$$

getting $c_1 = 2$ and $c_2 = 4$. Thus, the IVP has solution

$$\mathbf{x}(t) = e^{-3t} \begin{pmatrix} 2 + 4(t+1/4) \\ 2 + 4t \end{pmatrix} = e^{-3t} \begin{pmatrix} 3 + 4t \\ 2 + 4t \end{pmatrix}.$$

Mathematica's ParametricPlot[] command may be used to draw the solution's trajectory in the phase plane $(x_1x_2$ -plane); see left below. The graph on the right is that of $x_1(t) = e^{-3t}(3+4t)$.



7.8/#17(d) The third solution's form has already been suggested in the problem:

$$\mathbf{x}^{(3)}(t) = e^{2t} \left(\zeta + t\boldsymbol{\eta} + \frac{t^2}{2} \boldsymbol{\xi} \right).$$

We will not assume, at the outset, anything in particular about $\boldsymbol{\xi}$ or $\boldsymbol{\eta}$ (that is, we are not assuming that $\boldsymbol{\xi}$ solves $(A+2I)\boldsymbol{\xi}=\mathbf{0}$ nor that $\boldsymbol{\eta}$ solves $(A+2I)\boldsymbol{\eta}=\boldsymbol{\xi}$). What we do assume is that $x^{(3)}$ solves $\mathbf{x}'=A\mathbf{x}$. This means that, $\frac{d}{dt}\mathbf{x}^{(3)}=A\mathbf{x}^{(3)}$, or

$$e^{2t}\left(2\boldsymbol{\zeta}+2t\boldsymbol{\eta}+\boldsymbol{\eta}+t^2\boldsymbol{\xi}+t\boldsymbol{\xi}\right) = e^{2t}\left(A\boldsymbol{\zeta}+tA\boldsymbol{\eta}+\frac{t^2}{2}A\boldsymbol{\xi}\right).$$

Dividing through by e^{2t} and grouping some terms, we have

$$(A-2I)\boldsymbol{\zeta}+t(A-2I)\boldsymbol{\eta}+\frac{t^2}{2}(A-2I)\boldsymbol{\xi} = \boldsymbol{\eta}+t\boldsymbol{\xi},$$

an equation which must hold for all t. Because of this, the coefficients of the t^2 terms must match, as well as those of the t and constant terms. That is,

$$(A-2I)\boldsymbol{\xi} = \mathbf{0}, \qquad (A-2I)\boldsymbol{\eta} = \boldsymbol{\xi}, \qquad \text{and} \qquad (A-2I)\boldsymbol{\zeta} = \boldsymbol{\eta}.$$

So, though we did not presume it to be the case, $\boldsymbol{\xi}$ and $\boldsymbol{\eta}$ do solve the usual eigenvector and generalized eigenvector equations, while $\boldsymbol{\zeta}$ solves a similar equation as the one that $\boldsymbol{\eta}$ solves, only with right-hand side $\boldsymbol{\eta}$ instead of $\boldsymbol{\xi}$.

* The given matrix has the triple eigenvalue $\lambda = -5$, whose only linearly independent eigenvector is (-3, 1, 2). Thus we must solve $(A+5I)\eta = (-3, 1, 2)$ for η , and then solve $(A+5I)\zeta = \eta$ for ζ . The first of these, using Gaussian elimination, is

$$\begin{pmatrix} -2 & 4 & -5 & | & -3 \\ -1 & -3 & 0 & | & 1 \\ 3 & -1 & 5 & | & 2 \end{pmatrix} \qquad \begin{array}{c} \mathbf{r}_1 \leftrightarrow \mathbf{r}_2 \\ \sim \\ \end{array} \qquad \begin{pmatrix} -1 & -3 & 0 & | & 1 \\ -2 & 4 & -5 & | & -3 \\ 3 & -1 & 5 & | & 2 \end{pmatrix}$$

$$(-\mathbf{r}_1)
ightharpoonup \mathbf{r}_1 \ -2\mathbf{r}_1 + \mathbf{r}_2
ightharpoonup \mathbf{r}_2 \ \sim \ 3\mathbf{r}_1 + \mathbf{r}_3
ightharpoonup \mathbf{r}_3 \ \sim \ \begin{pmatrix} 1 & 3 & 0 & -1 \ 0 & 10 & -5 & -5 \ 0 & -10 & 5 & 5 \end{pmatrix} \ \mathbf{r}_2 + \mathbf{r}_3
ightharpoonup \mathbf{r}_3 \ \sim \ \begin{pmatrix} 1 & 3 & 0 & -1 \ 0 & 10 & -5 & -5 \ 0 & 0 & 0 & 0 \end{pmatrix} \ .$$

Taking η_3 (free) to be zero, the second row says

$$10\eta_2 - 5(0) = -5 \qquad \Rightarrow \qquad \eta_2 = -\frac{1}{2},$$

and thus the first row says

$$\eta_1 - 3\left(\frac{1}{2}\right) = -1 \qquad \Rightarrow \qquad \eta_1 = \frac{1}{2}.$$

So, $\eta = (1/2, -1/2, 0)$.

Now, we solve for ζ :

$$\begin{pmatrix}
-2 & 4 & -5 & | & 1/2 \\
-1 & -3 & 0 & | & -1/2 \\
3 & -1 & 5 & | & 0
\end{pmatrix}$$

$$\begin{array}{c|cccc}
\mathbf{r}_1 \leftrightarrow \mathbf{r}_2 & & \begin{pmatrix}
-1 & -3 & 0 & | & -1/2 \\
-2 & 4 & -5 & | & 1/2 \\
3 & -1 & 5 & | & 0
\end{pmatrix}$$

$$\begin{array}{c|cccc}
(-\mathbf{r}_1) \to \mathbf{r}_1 & & & \\
-2\mathbf{r}_1 + \mathbf{r}_2 \to \mathbf{r}_2 & & \begin{pmatrix}
1 & 3 & 0 & | & 1/2 \\
0 & 10 & -5 & | & 3/2 \\
0 & -10 & 5 & | & -3/2
\end{pmatrix}$$

$$\begin{array}{c|cccc}
\mathbf{r}_2 + \mathbf{r}_3 \to \mathbf{r}_3 & & & \begin{pmatrix}
1 & 3 & 0 & | & 1/2 \\
0 & 10 & -5 & | & 3/2 \\
0 & 0 & 0 & | & 0
\end{pmatrix}.$$

Once again, ζ_3 is free, and we take it to be zero. Thus,

$$10\zeta_2 - 5(0) = \frac{3}{2} \qquad \Rightarrow \qquad \zeta_2 = \frac{3}{20},$$

and

$$\zeta_1 + 3\left(\frac{3}{20}\right) = \frac{1}{2} \qquad \Rightarrow \qquad \zeta_1 = \frac{1}{20}.$$

So, $\zeta = (1/20, 3/20, 0)$, and the general solution is

$$\mathbf{x}(t) = e^{-5t} \left\{ c_1 \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix} + c_2 \left[\begin{pmatrix} 1/2 \\ -1/2 \\ 0 \end{pmatrix} + t \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix} \right] + c_3 \left[\begin{pmatrix} 1/20 \\ 3/20 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1/2 \\ -1/2 \\ 0 \end{pmatrix} + \frac{t^2}{2} \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix} \right] \right\}.$$